1 Time varying changes and uncertainties in the CMIP6 ocean carbon sink from global to regional

2 to local scale

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Abstract. As a major sink for anthropogenic carbon, the oceans slow the increase of carbon dioxide in the 8 atmosphere and regulate climate change. Future changes in the ocean carbon sink, and its uncertainty at a global 9 and regional scale, are key to understanding the future evolution of the climate. Here, we conduct a multimodel 10 analysis of report on the changes and uncertainties in the historical and future ocean carbon sink using output data 11 from the latest phase of the Coupled Model Intercomparison Project: Phase 6 (CMIP6,) multimodel ensemble and 12 13 observations compare to one observation based product. We show that the ocean carbon sink is concentrated in highly active regions - 70 percent of the total sink occurs in less than 40 percent of the global ocean. High pattern 14 correlations between the historical and projected future carbon sink indicate that future uptake will largely continue 15 to occur in historically important regions. We conduct a detailed breakdown of the sources of uncertainty in the 16 17 future carbon sink by region. Scenario Consistent with CMIP5 models, scenario uncertainty dominates at the global scale, followed by model uncertainty, and then internal variability. We demonstrate how the importance of internal 18 19 variability increases moving to smaller spatial scales and go on to show how the breakdown between scenario, 20 model, and internal variability changes between different ocean basins regions, governed by different processes. Moreover, Using the CanESM5 large ensemble we show that internal variability changes with time based on the 21 22 scenario, breaking the widely employed assumption of stationarity. As with the mean sink, we show that uncertainty in the future ocean carbon sink is also concentrated in the known regions of historical uptake. The resulting 23 patternsPatterns in the signal-to-noise ratio have strong implications for observational detectability and time of 24 emergence, which varies we show to vary both in space and with scenario. Our We show that the largest variations 25 in emergence time across scenarios occurs in regions where ocean sink is less sensitive to forcing - outside of the 26 highly active regions. In agreement with CMIP5 studies, our results suggest that to detect human influence 27 onchanges in the ocean carbon sink as early as possible, and to efficiently reduce uncertainty in future carbon 28

29 uptake, modelling and observational efforts should be focused in the known regions of high historical uptake,

30 including the Northwest Atlantic and the Southern Ocean.

31 **1. Introduction**

32 Recent increases in greenhouse gases have trapped additional heat relative to the pre-industrial era and raised 33 Earth's average temperature. Carbon dioxide (CO₂) is the primary driver of the global warming in the industrial 34 period (Masson-Delmotte et al., 2021). The concentration of atmospheric CO₂ has increased from approximately 277 parts per million (ppm) in 1750 (Joos et al., 2008), the beginning of the Industrial Era, to 409 ppm in 2019. 35 However, less than half of the CO_2 emitted by anthropogenic CO_2 -activity has remained in the atmosphere; the. 36 37 The remaining CO_2 has been was taken up by the natural carbon sinks of the ocean and the terrestrial biosphere. Specifically, the global ocean absorbed $\sim 26\%$ of the total CO₂ emissions during 2011-2020 (Friedlingstein et al., 38 2021). 39

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41 The ocean's capacity to absorb increasing amounts of anthropogenic CO_2 is not uniformly distributed (McKinley 42 et al., 2016, Sarmiento et al., 1998). Despite increasing atmospheric CO_2 concentrations, the air-sea CO_2 flux does 43 not change much in the subtropical gyres. The regions where ocean carbon uptake notably increases are those with strong exchange between the surface and the deep ocean (Ridge and McKinley, 2021; Frölicher et al., 2015; 44 McKinley et al., 2016). This response of the ocean carbon sink to increasing atmospheric CO₂ levels consists 45 of changes in both the anthropogenic and the natural carbon sink (Crisp et al. 2022, McKinley et al. 2020, 46 Hauk et al., 2020, Gruber et al. 2019, Frolicher at al, 2015). Even within regions there are large variations in the 47 sink. The Northeast Pacific, for instance, is a net sink for atmospheric CO₂. However, the region includes diverse 48 oceanographic areas such as open ocean, continental margins, and fiords, leading to large spatial variability 49 indominant mechanisms and the direction of the CO₂-sea-air flux (Sutton et al., 2017; Takahashi et al., 2006).carbon 50 sink. In the Southern Ocean, for instance, the spatial superposition of natural and anthropogenic CO_2 fluxes leads 51 to a relatively strong uptake band between approximately 55°S and 35°S (Gruber et al., 2019). However, south of 52 53 the Polar Front (55°S), the different estimates agree less well (Gruber et al., 2019). Supported by measurements based on biogeochemical floats (Bushinsky et al., 2019; Gray et al., 2018; Williams et al., 2018), Gruber et al. 54 55 (2019) argues argue that the region was most likely a small source in 2019.

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57 Earth System Models (ESMs) are the primary tool for projecting the future evolution of ocean carbon uptake on subannual to centennial timescales in the climate system. However, quantitative projections from ESMs across these 58 timescales are subject to considerable uncertainty, particularly at regional and local scales (Friedrich et 59 al., 2012; Frölicher et al., 2014; Hauck et al., 2015; Laufkötter et al., 2015; Roy et al., 2011; Tjiputra et al., 2014; 60 Terhaar et al., 2021) where less averaging is done and more diverse different individual mechanisms dominate-61 different regions. Projection uncertainty varies with lead time, spatial averaging scale, and from region to region-62 (Lovenduski et al., 2016; Schlunegger et al., 2020). For example, Lovenduski et al. (2016) showed a spatially 63 heterogeneous pattern of projection uncertainty in CO₂ flux projections over 17 ocean regions- for CMIP5 models. 64 Furthermore, by comparing uncertainty at the global scale to the scale of the California Current System, they show 65 that uncertainty was relatively is higher compared to the global scale. If at smaller scales. Schlunegger et al. (2020) 66 further shows different partitioning of uncertainty for 10 ocean basins at the year 2050. All said, if ESMs are 67 to be used to quantify future changes in ocean carbon uptake, especially across shorter timescales and at regional 68 spatial scales, and to inform observational campaign planning, their uncertainties must be well known and well 69 understood (Lovenduski et al., 2016). 70

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A systematic characterization of projection uncertainty has become possible with the advent of the Coupled Model Intercomparison Project (CMIP), as a number of climate models of similar complexity provided simulations over a consistent time period and with the same set of emissions scenarios (Lehner et al., 2020). We consider<u>There are</u> three main types of <u>projection</u> uncertainty in climate model projections, as described by Hawkins and Sutton (2009) (hereafter HS09):

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Uncertainty due to internal variability: Internal variability is the unforced natural climate variability resulting 78 from the internal processes in the climate system. Modes such as the El Niño-Southern Oscillation, North Atlantic 79 Oscillation, Atlantic Multidecadal Oscillation, Pacific Decadal Oscillation, and Southern Annular Mode (SAM) 80 contribute, along with others, to this internal variability. Internal variability also includes variability that acts on 81 shorter time and spatial scales, such as submesoscale and mesoscale ocean features (Frolicher et al., 2016). The 82 real world follows only one of an infinite possible number of *realizations* of internal variability, and due to its 83 chaotic nature, the future evolution of internal variability is not predictable beyond short timescales- (Somerville, 84 1987: Lorenz, 1969). Climate model simulations do not attempt to reproduce the exact observed evolution of 85 internal variability, but produce their own, unique realizations that aim to capture the correct statistics of this 86 variability. Hence, our analysis must account for internal variability, both when comparing historical model 87

simulations to observations, and when considering uncertainties in the future ocean carbon sink. In HS09, a fourth-88 order polynomial fit to simulated global and regional temperature timeseries represented the forced response, while 89 the residual from this fit represented the internal variability. However There is thus, an assumption of stationarity 90 (constant in time) in their method. Moreover, this approach could possibly conflate internal variability with the 91 forced response in cases where low-frequency (decadal-to-multidecadal) internal variability exists, or when the 92 forced signal is weak, which makes the statistical fit a poor estimate of the forced response (Kumar and Ganguly, 93 2018). In this study, we instead use a Single-Model Initial-condition Large Ensemble (SMILE) to robustly quantify 94 the simulated forced response and internal variability across time and scenarios using ensemble statistics (Lehner 95 et al., 2020). A SMILE is an ensemble of model realizations that each starts from different initial conditions but 96 uses the same model and forcing, and provides representations of the climate system that are equivalent except for 97 98 internal variability.

Uncertainty due to model structure: Each model has a specific way of representing the physical world. Models differ in their resolution, structure, numerics, and parameterization of processes. These differences cause models to respond differently to the same forcing. For example, the CMIP5 model simulations run under Representative Concentration Pathway 8.5 (RCP8.5) project a wide range of cumulative anthropogenic carbon storage by 2100 (320–635 Pg-C) (Ciais and Sabine, 2013) due to both internal variability and model uncertainty (Lovenduski et al., 2016).

105 Uncertainty due to emission scenario: The future of the climate system depends on human activity and our emission of climate active gases that change radiative forcing. Future emissions are highly uncertain, given our 106 inability to project the complex changes in society and technology upon which they depend. As a result, future 107 simulations are run with a range of possible "scenarios" for how future emissions (or atmospheric concentrations) 108 will evolve under different socioeconomic storylines. These scenarios are prescribed via the internationally 109 coordinated experiments organized by the Coupled Model Intercomparison Project. Since the future emission 110 trajectory is unknown, these future simulations are referred to as projections, rather than predictions. Projections 111 of future ocean carbon uptake from ESMs are greatly influenced by the choice of emission scenario (Lovenduski 112 113 et al., 2016). For example, cumulative ocean carbon uptake from 1850 is projected to saturate at approximately 290 114 \pm 30 GtC under ssp126, and to reach 520 \pm 40 GtC by 2100 under ssp585 for CMIP6 models (Canadell et al., 2021).the cumulative oceanic storage of anthropogenic carbon in CMIP5 models by 2100 ranges from 110-220 Pg-115 C under RCP2.6 to 320 635 Pg-C under RCP8.5 (Ciais and Sabine, 2013). 116

117 In this paper we Together with the patterns of changes in the sink, the patterns of internal variability allow for an assessment of the required timescales for detection of changes in the ocean carbon sink. Detection means that we 118 119 can robustly separate the forced signal from internal variability (McKinley et al., 2016). Detectability can be assessed using Time of Emergence (TOE; Hawkins and Sutton, 2012; Lovenduski et al., 2016; McKinley et al., 120 2016; Rodgers et al., 2015; Schlunegger et al., 2020 & 2019). For example, McKinley et al. (2016) and Schlunegger 121 et al. (2019) showed that the forced signal of increasing ocean carbon uptake is not detectable in the Ekman 122 convergence regions of the subtropical gyres. Schlunegger et al. (2020) builds on that using four large ensembles 123 of CMIP5 ESM simulations with two forcing scenarios to show that air-sea CO₂ flux TOEs show strong agreement 124 125 between the large-ensembles not just for global and regional scales but also locally and spatially. Their use of only four models and two scenarios however, potentially underestimates the contribution of model and scenario 126 127 uncertainty. 128 Here, we build on previous work using CMIP6 models. We make use of an ensemble of 13 models to better capture 129 model uncertainty in the response to different forcing (scenarios) and three scenarios to represent a wider range of 130 future possibilities including a strong mitigation scenario. We start by analysing the regional patterns of historical 131 132 ocean carbon uptake and how they are projected to change in the future (Sect. 3.1). We estimate internal variability 133 from a comprehensive SMILE, avoiding the stationarity assumption common in previous work, which we show is 134 violated. Then, we examine the partitioning among different sources of uncertainty (Sect. 3.2) and the scale

dependence of this partitioningprovide a novel analysis of how the three sources of variability change across the full continuum of scales (Sect. 3.3) to understand). Having Shown how the uncertainty and distribution among sources differ based on scale of integration and region of interest, we analyse local patterns of uncertainty by the source (Sect. 3.4). The final section explores the detectability of the model projected signal given the uncertainty imposed by internal variability₅. We report on the scenario-dependent Time of Emergence, using a scenario specific measure of internal variability in order to make useful suggestions for future observations.

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143 **2.Data and Methods**

144 <u>2.1 Model Data Selection</u>

145 Here we use results from models selected from the 6th Coupled Model Intercomparison Project (CMIP6; Eyring

- et al., 2016). Models are chosen based on availability, meaning all models that provided at least one realisation
- 147 for air-sea CO₂ flux (fgco2) for the <u>CO₂ concentration driven</u> experiments of interest. One realization of each
- 148 model over the historical period and three scenarios that represent the low (ssp126), mid (ssp245), and high
- 149 (ssp585) ranges of future atmospheric CO₂ concentrations are analysed. A total of 16 models met these criteria,
- out of which 3 were excluded as outliers (see section S1 in the Supplements). To maintain equal sampling, only
- 151 one realization of each model iswas selected, except when specifically using the large ensembles to assess
- internal variability. Finally, since the ocean component of the models may be on different grids, all model data
- are remapped to a regular one-by-one-degree grid. were remapped to a regular one-by-one-degree grid and a 10
- 154 year running mean filter was applied to the time-series. We did not account for potential drift in the models.
- 155 <u>However, the drift is known to be small in the models compared to the historical trends for CMIP5 models</u>
- 156 (Hauck et al, 2020). For 11 of our CMIP6 models for which piControl runs are available, on average, the drift is
- 157 more than one order of magnitude smaller than the change in the model scenario with the smallest trend over the
- 158 <u>21st century, on the global scale.</u>
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160 <u>2.2 Sources of uncertainty</u>

Three sources of uncertainty are considered following the approach of HS09. Total uncertainty is composed of
 internal, model, and scenario uncertainty in equation 1, which assumes that each of these sources is independent.
 Here, each source of uncertainty is considered as a function of time (*t*) and location (*l*) (Lovenduski et al., 2016):

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$$U_T^{2}(t, l) = U_I^{2}(t, l) + U_M^{2}(t, l) + U_s^{2}(t, l)$$
(1)

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where $U_T(t, l)$ is total uncertainty, $U_I(t, l)$ is internal variability, $U_M(t, l)$ is model uncertainty, and $U_S(t, l)$ is scenario uncertainty. The fractional uncertainties for each source are calculated as $\frac{U_I^2}{U_T^2}$, $\frac{U_M^2}{U_T^2}$, and $\frac{U_S^2}{U_T^2}$ (Lovenduski et

- 169 al., 2016).
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HS09 assume $U_l(t, l)$ to be constant in time (stationary) and use a 4th degree polynomial fit to measure internal 171 variability as the spread over time and scenario of the residuals for each models model's signal relative to the fitted 172 signal. We show in the Supplements (see section S2) that internal variability depends on time and scenario, so a 173 better estimate violating the commonly used assumption of internal variability should stationarity. Using a SMILE 174 allows us to account for these variations, without having to make any assumptions about distribution or stationarity 175 of variability (Frolicher et al., 2015; Schlunegger et al., 2020). Here, we quantifyestimate internal variability as 176 two times the standard deviation of the annual carbon sink across many 50 realizations from a Single Model Initial 177 Condition Large-ensemble based on CanESM5: (Eq. 2): 178

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$$U_{I}(t, l) = 2 \left| \frac{1}{Ns} \sum_{l=1}^{Ns} \text{Var} (Ca) \right|$$

$$= 2 \sqrt{\frac{1}{Ns} \sum_{s=1}^{N_s} \text{Var (CanESM5 Large Ensemble)}}$$
(2)

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where *s* indicates each scenario (*Ns* is the number of scenarios) and Var indicates the variance over the large ensemble of CanESM5. In the CanESM5 SMILE, each realization starts from different initial conditions which are drawn from points separated by 50 years in the piControl simulation. Thus, the spread across the realizations gives a robust estimate of the internal variability, including sampling over longer term ocean variability. Internal variability is an important component of the uncertainty that is not reducible and results from the chaotic nature of the climate system. Further details regarding the estimation of internal variability are explained in the Supplements (see section S2). CanESM5

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Previous studies have also used SMILEs to estimate variability (Frolicher et al., 2015; Schlunegger et al., 2020), 191 although they used either a limited ensemble size or single scenario. We show in the Supplements (Fig. S2), that a 192 193 sufficiently large ensemble size is needed to capture internal variability, and that internal variability depends on the scenario. In the ideal case, if every CMIP model provided sufficiently large SMILEs for each scenario, an ensemble 194 195 mean estimate of the variability could be obtained and would represent a best estimate (but still possibly biased compared to the real world). However, only a handful of CMIP6 models produced multiple ensemble members. 196 We selected the CanESM5 SMILE as it is the only model that has a large enough ensemble over the entire timeline 197 198 and set of experiments to make this estimate internal variability robustly and across scenarios.

The use of a single model to estimate the scale of internal variability leads to some uncertainty in our estimates, as models do not agree perfectly with each other on the variability. Nonetheless, over the historical period, variability between large ensembles from three models that have enough ensemble members is within 10%, on the global scale (Fig S3). Differences will be larger at smaller scales; however, the general patterns of the magnitude of internal variability (see Fig. S4) are in good agreement across models and are consistent with known regions of high variability in the observed ocean, validating our use of the CanESM5 SMILE

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Model uncertainty is calculated by taking the variance across the forced signal of all available models for each scenario, averaging over the three scenarios, and then reporting twice the square root of the result (Eq. 3).

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$$U_{M}(t,l) = 2 \sqrt{\frac{1}{Ns} \sum_{s=1}^{N_{s}} \operatorname{Var}_{m}(F(m,s,t,l))}$$
(3)

where Var_m means the variance taken across different models for individual times and scenarios, *m* indicates each model, and *t* stands for time. F(m, s, t, l) is the forced signal and can be related to each realization as follows:

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$$T(m, s, t, l) = F(m, s, t, l) + R(m, s, t, l)$$
⁽⁴⁾

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Where, T(m, s, t, l) represents the reported output, i.e. each realization, but must be corrected for internal 216 217 variability. R(m, s, t, l) is the residual from the forced signal caused by internal variability. Here, the variance in 218 the forced signal across all models is calculated by correcting the total variance across each modelall models' one 219 realization for the variance caused by internal variability. The corrections are done by subtracting the variance across the same number of CanESM5 ensemble members as the multi-model ensemble (13 members) from the 220 221 spreadvariance across the one realization of eachall of the 13 models. For this correction only, the sample sizes (13) are kept the same so that the internal variability removed from the variance across the models' first realizations 222 223 is not overestimated by a well sampled 50-member ensemble (see section S3 in the Supplements).

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 $U_s(t, l)$ is the scenario uncertainty. Scenario uncertainty is measured as twice the standard deviation (square root of variance) across scenarios of the multi-model mean signal (Eq. 5).

$$U_{S}(t,l) = 2 \sqrt{\operatorname{Var}_{m}(\frac{1}{N_{m}} \sum_{m=1}^{N_{m}} T(m, s, t, l))}$$
(5)

where N_m is the number of models. The multi-model mean across the first realizations of the 13 models gives the multi-model forced response and does not require correction for internal variability as done for model uncertainty before.

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We conduct analysis on three different scales: single grid point (one-degree resolution), regional, and global. When regional and global analysis is done, the dependence on location is taken away by integrating and averaging over that region or the whole global ocean.

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237 <u>2.3 Time of Emergence (TOE)</u>

In order to know when the forced response is distinguishable from internal variability, time of emergence<u>TOE</u> is calculated following the approach of McKinley et al. (2016). The time of emergence is the first year when the multi-model mean anomaly is larger than internal variability – <u>approximated by</u> two times the standard deviation across the 50 member CanESM5 ensemble - for five consecutive years (the first year of this five-year period is reported as the time of emergence). The result is reported at each grid point for the 10-year running mean smoothed anomaly relative to the 1995-2015 mean (detection of a change relative to the current state of the ocean).

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246 <u>2.4 Scale Dependence</u>

Finally, the scale dependence of the sources of uncertainty is measured at year 2050 using ssp245 for internal variability and model uncertainty, and using all scenarios for scenario uncertainty. The analysis is done by moving a sliding sample window of a given area across the earth, and then repeating with a larger and larger window until all scales from $<100 \text{ km}^2$ to the whole Earth are considered. The For each source of uncertainty and averaging scale, the average for all rectangles of across the globe is reported, where each rectangle contains the same ocean area across the global ocean for each source of uncertainty is reported.

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254 **3. Results and Discussion**

255 <u>3.1 Global Analysis</u>

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The pattern of the carbon sink in the CMIP6 multi-model ensemble mean from the historical experiment over 1995-256 257 2015 matches that of the Landschützer (2016) Self Organizing Map - Feed Forward Neural Network (SOM-FFN) observation-based data product estimate (correlation coefficient of 0.84, compare Figs. 1a and 1b). We use the 258 259 multi-model mean response to external forcing as a more robust estimate of the forced climate signal than the response of any single model (Tebaldi & Knutti, 2007). Unlike in ESMs, the observation-based product only 260 represents the one realization of the real world, which includes internal variation, and is therefore not directly 261 equivalent to the forced signal. However, the comparison to the 20 year mean multi-model mean still informs us 262 263 about the degree of agreement between the two products. When compared to the observation-based data product, the CMIP6 multi-model mean shows a larger sink (positive flux) in the North Atlantic and North and North-West 264 Pacific but a smaller sink in the Southern Ocean (Fig 1a, b). Additionally, the observation-based data product shows 265 a larger source in the Equatorial Pacific and Indian Ocean than the CMIP6 multi-model ensemble. 266

- 268 While most of the global ocean shows a net sink relative to the pre-industrial era, the largest change takes place in some highly active regions such as the subpolar North Atlantic, Southern Ocean, Eastern Equatorial Pacific, and 269 western boundary currents of the mid-latitude gyre systems in the Pacific and Atlantic Oceans (Fig. 1c). These 270 regions of largest change in the carbon sink (anthropogenic plus changes in the natural carbon sink-seem to be) are 271 the regions where there is a surface-depth connectivity. We refer to these regions as "hotspots" from here on the 272 air-sea flux of anthropogenic carbon is fundamentally limited by the rate of surface-to-depth transport (Graven et 273 al., 2012; Ridge and McKinley 2021). These results for CMIP6 models are consistent with those for CMIP5 models 274 shown by McKinley et al. (2016).) and earlier studies such as Sarmiento et al. (1998). Here, we provide a new 275 metric for quantifying these highly active regions. We find that for all three scenarios and both mid-21st century 276 277 (2040-2060 mean) and late- 21st century (2080-2100 mean) time periods (with the exception of ssp126 late-century where strong mitigation of anthropogenic CO₂ emissions results in broad patterns of negative anomalies), 278 279 approximately 70% of the changes in the sink relative to the preindustrial area takes place in less than 40% of the global ocean (see Supplement Fig. S7 and section S5). 280
- The regions of largest future carbon uptake, relative to the 1995-2015 mean, are <u>within the same highly active</u> regions responsible for most of the uptake over the historical period. The correlation coefficients onat the top of
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each panel in Fig. 1 (except 1b) represent the <u>pattern</u> correlation between future absolute anomalies, relative to 1995-2015, and anomalies in 1995-2015, relative to the pre-industrial era. The high correlations indicate that regions that have been most active in carbon sequestration since the pre-industrial era are the same regions that will continue to change most into the future, particularly with larger increases in atmospheric $CO_2(ssp585)$. <u>Our results</u> support the findings of Wang et al. (2016) who showed that projected future air-sea CO_2 fluxes are strongly associated with simulated historical air-sea CO_2 fluxes. This confirms that the historical state is a good predictor for the future state (Wang et al., 2016) not only in terms of magnitudes of the sink, but also in the spatial pattern.

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Figure 1- CMIP6 multi-model mean maps <u>of carbon sink and sink anomalies</u> using one realization of each model. Columns represent different time periods, being the recent time (1995-2015 mean), mid-century (2040-2060 mean), and late-century (2080-2100 mean). Note: the sink is positive into the ocean. The first column shows (a) the <u>earbon sinkCMIP6 ensemble</u> mean air-sea CO₂ flux over 1995-2015, (b) Landschützer et al. (2016) SOM- FFN product, and (c) the <u>CMIP6 ensemble</u>

299 <u>mean flux</u> anomaly relative to the 1850-1900 mean. Other panels are anomalies relative to the 1995-2015 multi-model mean 300 (panel a). Panels d through i show different scenarios. Numbers above each map are correlation coefficients between the 301 absolute value of the change relative to 1995-2015 with the 1995-2015 anomaly map relative to the pre-industrial era in 302 panel c, except the red number at the top of panel b that is the correlation coefficient with this panel and panel a.

The multi-model mean sink anomalies for two future periods, 2040-2060 and 2080-2100, show how the sink is 304 projected to evolve, relative to 1995-2015, according to time and choice of emission scenario (Fig. 1d-i). The 305 regional patterns show mostly positive anomalies at mid-century- with largest changes in the higher emission 306 scenarios (ssp585). Towards the end of the century, however, broader patterns of negative anomalies are expected 307 in ssp126, as emissions turn negative in the late-century in this scenario. The largest absolute values of anomalies 308 309 are still within the same highly active regions discussed before with surface-depth connectivity regardless of it 310 being positive or negative. The late-century anomalies are predominantly positive in ssp585 which corresponds to the highest emission scenario, (continuing to grow larger compared to the mid-century), while ssp245 is somewhere 311 in between, with regions of positive and negative anomalies. Under ssp245, as CO₂ emissions decrease and 312 atmospheric CO₂ start to level off, the intensity of uptake decreases in the midlatitude western boundary currents 313 314 and subpolar North Atlantic in the late-century, and anomalies in the Eastern Equatorial Pacific also decrease, compared to the mid-century. The globally integrated ocean carbon uptake rates are summarized in Table 1. 315



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Figure 2- (a) Thick lines are multi-model means of the global mean ocean carbon sink anomaly timeseries relative to 1995-2015. Individual models averaged for the means are plotted as thin grey lines in the background. The black dashed line shows the Landschützer et al. (2016) SOM-FFN product. Both models and SOM-FFN timeseries are smoothed with a 10-year running mean. The blue dashed lines show internal variability for ssp245. (b) Timeseries showing the breakdown of uncertainty to different sources with time for the global ocean carbon sink anomaly. The internal and model uncertainty are averaged for different scenarios.

	Scenario	1995-2020	2020-2040	2040-2060	2060-2080	2080-2100
Anomaly (range)	ssp126 ssp245 ssp585	0.00 (-0.06 – 0.06)	$\begin{array}{c} 0.13\\ (0.05-0.21)\\ 0.17\\ (0.08-0.24)\\ 0.22\\ (0.11-0.30)\end{array}$	$\begin{array}{c} 0.07\\ (-0.02-0.16)\\ 0.25\\ (0.11-0.36)\\ 0.49\\ (0.29-0.62)\end{array}$	$\begin{array}{c} -0.08\\(-0.14-0.01)\\0.23\\(0.09-0.33)\\0.71\\(0.45-0.90)\end{array}$	$\begin{array}{r} -0.24 \\ (-0.30.12) \\ 0.13 \\ (0.02 - 0.21) \\ 0.80 \\ (0.54 - 1.00) \end{array}$
Internal (model) Uncertainty	ssp126 ssp245 ssp585 Average	0.032 (0.08)	0.033 (0.11) 0.032 (0.11) 0.033 (0.13) 0.033 (0.12)	0.034 (0.11) 0.034 (0.14) 0.037 (0.2) 0.035 (0.16)	0.035 (0.10) 0.037 (0.14) 0.045 (0.26) 0.039 (0.18)	0.036 (0.11) 0.036 (0.12) 0.043 (0.27) 0.038 (0.18)

Table 1- CMIP6 multi-model mean globally averaged carbon sink anomalies (with ranges within the 20-yr period in parentheses) relative to the 1995-2015 mean (in mol-C m⁻² yr⁻¹) and Internalinternal variability from CanESM5 (with model uncertainty in parentheses) for the globally averaged ocean carbon sink anomalies for the three scenarios and the average values across scenarios.

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348 The trends in the global mean ocean carbon sink anomalies over 1995-2015 are statistically consistent between the CMIP6 multi-model ensemble mean and the Landschützer et al. (2016) observation-based data product (Fig. 2-a), 349 350 based on the test from Santer et al. (2008); see Supplements section S5). However, the SOM-FFN based timeseries shows a larger multi-decadal variability (variations in the 10-year running mean timeseries on top of the 351 trend) than seen in individual model realizations, and is larger than the range of internal variability estimated from 352 the CanESM5 SMILE. The difference could be due to either overestimation of internal variability by the SOM-353 354 FFN method, or underestimation of the internal variability infrom the modelsESMs. Given that on regional scales 355 the SOM-FFN data is within the range of internal variability projected by the CMIP6 large-ensemble of CanESM5

(see Sect. 3.3), and that there are significant gaps in the spatial and temporal sampling that underlies the Landschützer et al. (2016) estimate, it seems plausible that the discrepancy is largely due to overestimation of internal variability on the global scale by the SOM-FFN technique. This is consistent with the findings of Gloege et al. (2021), which showed that, globally, the magnitude of decadal variability is overestimated by 21% by the SOM-FFN technique, attributed to the amount of data filling.

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On the global scale, model uncertainty is the dominant source of uncertainty in the historical period, but scenario 362 uncertainty comes to dominate later (Fig. 2b). Over the 1995-2020 period, model uncertainty explains around 85% 363 of the total uncertainty. Scenario uncertainty becomes the dominant source after 2040, explaining almost 40% of 364 the total uncertainty at that time and more than 90% by the end of the century. Internal variability explains 15% at 365 366 the start of the century but only around 1% by the end. It is worth mentioning that the decreased shares of uncertainty associated with model and internal variability do not mean that model or internal variability decrease 367 368 in an absolute sense; rather, their importance relative to scenario uncertainty declines. InternalThese results 369 regarding the importance of model and scenario uncertainties for multidecadal projections, and dominance of 370 scenario uncertainty with time agree with previous studies using CMIP5 models (Lovenduski et al., 2016; 371 Schlunegger et al., 2020).

373 Absolute internal and model uncertainty of the global carbon sink change with time, based on the scenario (Table 2); high, Fig. S3). High emission scenarios such as ssp585 show a larger change for both internal and model 374 375 uncertainty- where the forcing is stronger (Fig. S3). When averaged for the three scenarios, a constant absolute increase in the magnitudes of both model and internal variability is seen through the century until 2080-2100 when 376 the values either do not change or decrease slightly (Table 1). Model uncertainty more than doubles towards the 377 end of the century compared to 1995-2015 on average for different scenarios. This is consistent with Lovenduski 378 et al. (2016) who argues that the increase is due to difference in climate sensitivities between models that manifest 379 380 more strongly with time (and hence cumulative emissions). Additionally, the dependence of internal variability on the scenario is an interesting result. Future SMILEs from multiple models will allow evaluation of the degree of 381 dependence and the driving mechanisms of such changes with time based on the forcing (scenario). Our result of 382 internal variability dependence on scenario implies that the time of emergence of a signal out of internal variability 383 384 will be affected by changes in the internal variability under different future forcing scenarios – which we return to in Section 3.4. 385

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388 <u>3.2 Dependence of the sources of uncertainty on spatial scale</u>

It is generally accepted that uncertainty and, most importantly, internal variability grow larger as the averaging 389 (integration) scale gets finer, because on larger scales the variability is averaged out. Lovenduski et al. (2016) 390 391 showed this scale dependence by comparing an area covering the California Current System with the global ocean. 392 Here, we provide a Here, we provide a novel and continuous view of change in variability across scales from the 393 global to grid scale, by measuring how variability changes relative to scale on average (Fig. 3). At the global scale, the dominant source of uncertainty is scenario uncertainty, followed by model and internal variability respectively, 394 395 consistent with Fig. 2b. However, as the averaging (integration) scale gets finer, model and internal variability grow rapidly, while scenario uncertainty only grows slightly on average (over all regions of this size). At an 396 397 averaging (integration) scale with an area finer than 75 million km² (on average around the globe), model uncertainty becomes the dominant source of uncertainty, and at a scale finer than 3 million km², internal variability 398 becomes larger than scenario uncertainty. However, while this holds true on average over the globe, scale 399 dependence can vary in its nature depending on the particular region being sampled. The idea of scale dependence 400 401 of these uncertainties was tested in Lovenduski et al. (2016) by comparing an area covering the California Current System with the global ocean. Here, we provide a novel analysis on a continuum of scales covering global to 402 403 regional to local scales. While the results here hold true on average over the globe, scale dependence is partially controlled by the particular region being sampled. Finally, while our estimates of the magnitudes of sources of 404 uncertainty and the cross over points at which the dominance of internal variability over model uncertainty and 405 model uncertainty over scenario uncertainty takes place, depend on the choice of ESMs and the method for 406 calculation of internal variability, the general patterns are unlikely to be model dependent. 407

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Figure 3- Sources of uncertainty versus area of averaging. Internal variability is based on ssp245 year 2050 of all CanESM5 members. Scenario uncertainty is based on all scenarios of the 13 models at year 2050 and model uncertainty is the corrected standard deviation of our 13 models at year 2050 of ssp245. The values of uncertainties are averaged over all different rectangular areas of each size that can scan the globe. Dashed lines indicate the size of the averaging window and not a specific location.

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418 <u>3.3 Regional Analysis</u>

419 The We further expand on the findings of our analysis of the globally averaged scale dependence analysis were tested of uncertainty averaged over the globe by repeating the uncertainty breakdown for two specific regions: one 420 between 2040°- 60° N in the North EastNortheast Pacific (NE Pacific) between 130°- 160° W and one in the North 421 WestNorthwest Atlantic (NW Atlantic) between 40°- 70° W at the same latitude. We chose these regions, first, to 422 be of the similar size, and second to represent very different carbon dynamics. The NW Atlantic region represents 423 a hotspot highly active region while the NE Pacific region is more typical of quiescent ocean regions. By quiescent 424 ocean regions we refer to regions, where strong stratification limits the vertical transport of carbon by isolating the 425 surface the flux anomalies are relatively small. 426

427

The variation across scenarios is at all times smaller than internal variability in the NE Pacific (Fig. 4a). This 428 suggests both that it will be difficult to robustly detect any human induced changes in observations of the NEP 429 carbon sink, and that potential future differences relating to choice of mitigation scenarios will not be readily 430 apparent in the NE Pacific carbon flux. This is true even for the high emission scenarios, because the anomalies 431 are small regardless of scenario (Table 2). We speculate that in the absence of mechanisms providing a pathway 432 to the depth where significant CO_2 accumulation occurs, the surface pCO₂ trend will follow that of the 433 atmosphere closely, causing ΔpCO_2 and therefore air-sea carbon flux to remain fairly constant for all scenarios. In 434 the NW Atlantic however, the deviation across scenarios becomes larger than the internal variability in the early 435 436 2060s (Fig. 4c). The response of the region to climate change is dependent on the scenario (Table 2), or, in other 437 words, the amount of carbon dioxide in the atmosphere. This is because the NW Atlantic is a hotspothighly active region where the air-sea flux actively responds to the atmospheric CO₂ concentration. The connection to depth 438 allows for surface water to be replaced with water masses whose pCO₂ trend lags behind that of atmosphere. The 439 trend of the CMIP6 multi-model time-series over the historical period is statistically consistent (Santer et al., 440 441 2008See Supplements section S5) with that of the observation-based SOM-FFN product, and the multi-decadal variability is within the range of internal variability measured by the CanESM5 large-ensemble in both regions. 442 We note that both of these regions are relatively well sampled, which may lead to more robust estimates of multi-443 decadal variability in the Landschützer et al. (2016) dataset, and better agreement with the models than seen at 444 the global scale. 445

446

Fractional estimates of each source of uncertainty vary with time and have different patterns for these two regions. 447 448 Internal variability and model uncertainty in the NE Pacific and NW Atlantic are larger by an order of magnitude 449 than at the global scale (Table 2). A lesser importance for scenario uncertainty and greater importance for internal and model uncertainty is apparent in both regions compared to the global scale, in agreement with Schlunegger et 450 451 al. (2020). Over the period 1995-2020, model uncertainty is the dominant source of uncertainty in both the NE Pacific and NW Atlantic (80-90%), while the remainder is internal variability (Fig. 4bd). Internal variability 452 453 explains around 25-30% of the total uncertainty in the NE Pacific throughout the century. In the NW Atlantic 454 however, its share drops to 15% by the end of the century. The share attributable to internal variability is much larger during the 21st century in both regions compared to the global scale. Internal variability is larger in the NW 455 Atlantic in an absolute sense (Table 2), but its share of the total uncertainty is larger in NE Pacific (Fig. 4b). The 456 457 large share of internal variability in NW Pacific indicates the need for sustained observations in the region. Overall, internal variability averaged over the scenarios shows a small increase, but no clear trend in time in both regions 458

until the 2080-2100 period where it decreases, consistent with the global estimates. The dependence of internal variability on the scenario is an interesting result which requires further evaluations to understand the degree of dependence and the driving mechanisms of such changes with time based on scenario. (Table 2). We showed earlier that in the NE Pacific scenarios do not differ much asbecause the region is not a hotspotahighly active region(Fig. **S7**) - scenario uncertainty explains less than 20% of the total uncertainty at the end of the century in the NE Pacific. In the NW Atlantic, scenario uncertainty grows larger with time, becoming 45-50% of total uncertainty by the end of the century. In both regions, model uncertainty is the dominant source of uncertainty in all years. Our regional analysis confirms that while uncertainty and its distribution among sources depends on the spatial scale of integration, the specific location also matters (Lovenduski et al, 2016; Schlunegger et al., 2020). Schlunegger et al., (2020) tested this idea for 10 ocean basins but with different sizes (see their Figure 9). We focused on keeping the sizes similar and analyse a highly active region versus a more quiescent ocean region. The key message here that there is an association with the importance as well as the magnitude of sources of uncertainty with how active the region is in regards to the carbon sink is not sensitive to the use of CanESM5 for estimation of internal variability. Local patterns of uncertainty broken down by source are thus needed to clarify changes based on location.





Figure 4- (a), (c) Thick lines are multi-model mean timeseries of anomalies relative to the 1995-2015 mean. All model timeseries averaged for the means are plotted in grey lines in the background. The black dashed line shows the Landschützer et al. (2016) SOM-FFN product. The blue dashed line shows the internal variability measured as two times the standard deviation across all 50 members of CanESM5 only for ssp245 here. (b), (d) time-series showing the breakdown of uncertainty to different sources with time. The internal and model uncertainty are averaged for different scenarios. (a), (b) NE Pacific (40-60 °N, 130-160 °W). (c), (d) NW Atlantic (40 - 60 °N, 40-70 °W)

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		Scenario	1995-2020	2020-2040	2040-2060	2060-2080	2080-2100
NE	Anomaly (range)	ssp126 ssp245 ssp585	0.00 (-0.98 – 0.76)	$\begin{array}{c} 0.05\\ (-0.91-0.86)\\ 0.06\\ (-0.86-0.83)\\ 0.11\\ (-0.73-0.79)\end{array}$	$\begin{array}{c} 0.03\\ (-0.86-0.62)\\ 0.09\\ (-0.74-0.81)\\ 0.21\\ (-0.61-0.86)\end{array}$	$\begin{array}{r} -0.13 \\ (-1.1 - 0.58) \\ 0.03 \\ (-0.65 - 0.60) \\ 0.29 \\ (0.22 - 0.94) \end{array}$	$\begin{array}{r} -0.21 \\ (-1.18 - 0.60) \\ 0.06 \\ (-0.70 - 0.53) \\ 0.2 \\ (-0.25 - 0.98) \end{array}$
Pacific							
	Internal (model) Uncertainty	ssp126		0.47 (0.87)	0.43 (0.74)	0.40 (0.81)	0.39 (0.83)
		ssp245	0.30(0.00)	0.46 (0.87)	0.47 (0.81)	0.48 (0.64)	0.45 (0.53)
		ssp585	0.39 (0.90)	0.45 (0.81)	0.47 (0.745)	0.58 (0.55)	0.44 (0.57)
		A					
		Average	0.39 (0.90)	0.46 (0.86)	0.46 (0.77)	0.47 (0.70)	0.43(0.67)
	Anomaly (range)	ssp126 ssp245	0.00 (-0.97 – 1.31)	0.13 (-0.77 - 1.21) 0.18 (-0.78 - 1.23)	-0.20 (-1.03 – 0.56) 0.10 (-0.68 – 0.80)	-0.66 (-1.450.11) -0.20 (-0.97 - 0.50)	-1.00 (-1.800.56) -0.54 (-1.22 - 0.07)
		ssp585		0.23 (-0.70 – 1.20)	0.38 (-0.41 – 1.12)	0.41 (-0.27 – 1.29)	0.10 (-0.70 - 0.96)
NW							
Atlantic	C Internal (model) Uncertainty	ssp126		0.47 (0.91)	0.47 (0.79)	0.46 (0.78)	0.42 (0.80)
		ssp245	0.43 (1.02)	0.47 (0.96)	0.49 (0.82)	0.49 (0.80)	0.47 (0.79)
		ssp585		0.50 (0.90)	0.51 (0.94)	0.52 (1.00)	0.53 (1.00)
		Average	0.43 (1.02)	0.48 (0.93)	0.49 (0.87)	0.49 (0.88)	0.48 (0.88)

Table 2- CMIP6 multi-model mean sink anomalies (with ranges in parentheses) relative to 1995-2015 mean (in mol-C m⁻²
 yr⁻¹) and internal variability (with model uncertainty in parentheses) for the three scenarios and their average values in NE
 Pacific and NW Atlantic.

The regional analysis shows that while uncertainty and its distribution among sources depends on the spatial scale 510 511 of integration, the specific location also matters. Regional patterns of uncertainty broken down by the source are 512 needed to clarify changes based on location. Consistent with the sink anomaly maps (Fig. 1), the regions that show 513 highest uncertainty for any of the sources in the future, are the same regions that show the largest uncertainties in the historical period (Fig. 5). More importantly, the regions of largest future uptake uncertainty are highly correlated 514 with the historical regions of largest uptake, as shown by the pattern correlation coefficients above each panel. This 515 is a highly significant finding, because it suggests that knowledge of the regions of modern day surface carbon flux 516 anomaly provides us with information about regions of future uptake uncertainty. 517

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The regions of high internalInternal variability (from CanESM5 is most dominant in mid-latitude eastern 519 boundary upwelling regions, and their extensions, in the North Atlantic, in the western boundary currents of the 520 Gulf Stream and Kuroshio, and their extensions, and in the Southern Ocean) (Fig. 5). There is wide agreement 521 522 between different models and estimation methods in regions of largest internal variability (Fig. S4). The regions 523 of large internal variability are mostly within hotspots but are not confined to them and do not include all of 524 them. This lack of correspondence explains why the correlated with the same highly active regions for the sink anomalies discussed earlier (Fig 1c). However, correlation coefficients are not high for between internal 525 variability and historical uptake are lower than those seen for scenario and model uncertainty. An increase in 526 internal variability with time is seen mostly in regions such as the Southern Ocean, the Arctic Ocean, and 527 boundaries of the gyre systems, while the rest of the ocean does not show a clear change. The maps in Figure 5 528 are averaged over the three scenarios, which masks the changes to some extent. However, we show in the 529 Supplements (see section S2) that changes in the globally averaged internal variability with time are different for 530 different scenarios. 531

Model uncertainty is consistently highest in the hotspothighly active regions, (Figure S7), leading to
 strongerstrong correlation with the anomaly maps of Fig. 1e.1c. In these regions, ocean -circulation impacts
 surface pCO₂ through advection and water mass transformation regionally (Bopp et al., 2015; Toyama et al.,

535 2017) and models have substantial differences in ocean circulation. Ridge and McKinley (2021) suggest that while global surface carbon fluxes and carbon storage are largely similar across ESMs over the historical period, 536 consistent with the external forcing from atmospheric pCO_2 growth being the main driver of the historical sink 537 (McKinley et al., 2020), uncertainties in ocean circulation may become important in the future under a changing 538 trajectory of atmospheric boundary conditions. The model uncertainty is largest in the Southern Ocean, where 539 consistent with CMIP5 models (Frölicher et al., 2015). Here, mode and intermediate waters are formed, and the 540 complex time-evolving nature of the sink varies on all time- scales (Gruber et al. 2019). Frölicher et al. (2015) 541 note the largest disagreement in ocean carbon uptake between models is in the Southern Ocean because the exact 542 543 processes governing heat and carbon uptake remain poorly understood. The importance of model uncertainty in 544 the Southern Ocean provides a clear focal point for modelling centrescenters to concentrate their efforts in 545 reducing projection uncertainty. Atmospheric teleconnections might play an important role in generating the highly variable Southern Ocean carbon sink on decadal scales, and these are poorly constrained and represented 546 by models (Gruber et al. 2019). 547

548

Scenario uncertainty exhibits the largest change with time. This is by construction, meaning that as the scenarios 549 550 are designed to deviate from each other as with time goes forward to represent a range of pathways for future socio-economic possibilities in order to assess the long-term impacts of short-term decisions (Riahi et al., 2017). 551 Importantly, the correlation coefficients are highest between scenario uncertainty and the current sink regions, 552 indicating that the hotspotsame highly active regions are the regions that show the largest divergence among 553 scenarios, and that the sink in most other regions does not respond as strongly to scenario differences. We 554 showed an example of this earlier, where the timeseries of the multi-model signals for the three scenarios did not 555 556 emerge out of internal variability in the NE Pacific by 2100, whereas they did for the hotspot-highly actrive region of the NW Atlantic. This shows that, with pCO₂ differences across the air-sea interface being the main 557 driver of the sink (Fay & McKinley, 2013; Landschützer et al., 2015; Lovenduski et al., 2007; Mckinley et al, 558 559 2020; McKinley et al., 2017), the sink in these active hotspot regions, the sink evolves according to atmosphereas the atmospheric CO₂ concentration via changes because ocean processes that associated with surface-depth 560 561 connectivity constantly keep the surface ocean CO_2pCO_2 out of equilibrium with the atmosphere. In other words, 562 the surface water in these regions are constantly renewed, mostly through advection and water mass formation, with water masses whose pCO₂ has not increased at the same rate as the atmosphere. Elsewhere, these conditions 563 do not hold true and water at the surface equilibrates with the atmosphere on shorter time scales, decreasing the 564

sensitivity to the projection scenario. These uncertainties are central to the ability to detect human induced trends
 in observations of the surface ocean carbon flux as well as to assess mitigations or make societal decisions, to
 which we now turn.

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Figure 5- Sources of uncertainty averaged over the 20 year mean periods. The rows represent different sources as explained in the methods section at each grid cell. Columns represent different times: the recent (1995-2015), midcentury (2040-2060), and late-century (2080-2100) anomalies relative to the 1995-2015 mean. The numbers are correlation coefficients of each map with the 1995-2015 mean anomaly relative to the 1850-1900 mean (Fig. 1c).

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575 <u>3.4 Detectability</u>

576 Detectability refers to the ability to robustly identify a forced signal, above and beyond the noise induced by internal 577 climate variability. UnderstandingPrevious studies have largely presented a single time of emergence (Lovenduski

678 et al. 2016, Schlunegger et al., 2019, McKinley et al., 2016). However, understanding the regional differences,

timescales, and scenario dependence in the detectability of human induced trends in the ocean surface carbon flux
is important for informing observational strategies that aim to measure these changes.

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We measure the detectability of the CMIP6 multi-model ensemble mean ocean surface carbon flux anomaly using the time of emergence at each grid point. We use this finest scale as it is the most applicable to observational communities for sampling. The time of emergence is defined as the point at which the forced signal, given by the multi-model ensemble mean flux anomaly, relative to 1995-2015, emerges from internal variability, given by the CanESM5 SMILE.

587

The signal in human induced surface ocean carbon flux emerges beyond the internal variability earlier in the 588 hotspothighly active regions than anywhere else. This is evident in the Equatorial Pacific, Southern Ocean, the 589 western boundary currents of the gyre systems, and their extensions (Fig. 6). The fixed inactiveOcean regions, such 590 591 as the centres of the mid-latitude gyre systems and the NE Pacific, show late emergence times and, in some cases, no detectability of the signal in any of the scenarios by 2100. Convergent large-scale circulation and strong 592 593 stratification in these regions isolates the surface from the deep ocean reducing their capacity to hold large amounts 594 of carbon (McKinley et al., 2016). An absence of mechanisms constantly drawing surface ocean CO₂ out of equilibrium with atmospheric CO₂ lets the surface water equilibrate with and adjust to the atmosphere on short time 595 596 scales. Significant changes thus do not take place in the sink as the atmospheric CO₂ levels change and scenario uncertainty is lowest in the same regions (see Fig. 4). This is consistent with the results from Sect. 3.3, in which 597 we showed that internal variability is a significant source throughout the century in the NE Pacific, with scenarios 598 never emerging out of the range of internal variability (Fig. 4a,b). This result argues for focusing observational 599 efforts on the hotspot4a, b). Our results for the broad patterns in the multi-model mean TOE are largely consistent 600 with previous studies, suggesting they are robust and insensitive to for the method of estimating internal variability. 601 These include studies from CMIP5 models such as McKinley et al., (2016) that assumed time/scenario independent 602 internal variability, and Schlunegger et al., (2020) that used only high emission scenario internal variability from 603 four large ensembles to show there is strong agreement between LEs TOE both locally and spatially. Our results 604 argue for focusing observational efforts on the highly active regions in order to detect human influence on the ocean 605 carbon sink. Meanwhile, they imply that observational timeseries in quiescent regions, such as Ocean Station Papa 606 607 in the NE Pacific, need to interpret any observed trends with care, since internal variability tends to dominate over 608 human induced trends.

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Figure 6- Time of emergence of the multi-model mean anomaly under different scenarios. White regions indicate
where the anthropogenic signal cannot be detected even towards the end of the century.

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Previous studies have largely presented a single time of emergence; however, the time of emergence strongly 616 depends on the future scenario. The time of emergence Time of emergence strongly depends on the future scenario. 617 Schlunegger et al. (2020) show for two scenarios that modest (~10 yr) TOE differences between different ESMs 618 under strong anthropogenic forcing can evolve into pronounced (60+ yr) TOE differences with moderate 619 mitigation. Here, we make use of three scenarios including a strong-mitigation scenario and account for scenario 620 dependence of internal variability in our approximation using CanESM5. On average, scenarios with smaller forced 621 trends emerge later as the size of the forced trend is critical to the time of emergence (Fig. 2-a). The TOE is 622 623 earliest on average over the global ocean in ssp585, while it is later in ssp245, and later still in ssp126. The earlier 624 times of emergence are largely due to the stronger signal in ssp585, and weaker in ssp245 and ssp126 (Fig. 2-a), 625 consistent with the imposed changes in atmospheric CO₂ concentration.- The exceptions are quiescent regions that show earlier detectability for ssp126 compared to other scenarios; these exceptions are associated with larger (but 626 negative) anomalies in the latter half of the century under ssp126 which has negative emissions (compare panels 627 d-f, and g-i on Fig. 1). Internal variability does evolve somewhat differently for each scenario, but this is secondary 628 (Fig. B2).S2). Schlunegger et al. (2020) argues that variables such as air-sea CO_2 flux which are sufficiently 629 sensitive to emissions emerge early, prior to significant divergence among future scenarios. Consistent with this 630 result, our results indicate that there is broad agreement between scenarios in the TOE patterns, when considering 631 the highly active regions. Interestingly, our scenario-specific TOE shows that differences between scenario TOEs 632 is associated with how sensitive different regions are to emission scenarios. More specifically, comparison to the 633 maps of scenario uncertainty (Fig. 5) shows that TOE differs more across scenarios in regions where scenario 634

635 uncertainty is small, such as the aforementioned subtropics Ekman convergence regions. Elsewhere, the emergence 636 happens before scenarios diverge significantly. Our results suggest that under the rapidly rising atmospheric CO₂ 637 concentrations seen in ssp585, the human signal in the ocean carbon sink will be detectable across much of the 638 global ocean over the coming few decades. However, under strong mitigation scenarios, such as ssp126, early 639 emergence (earlier than 2030) will only occur in isolated regions- while counter-intuitively, less percentage of the 640 global ocean remains non-emergent by 2100.

641 4. Conclusions

Ocean carbon uptake as a result of the increasing atmospheric CO_2 concentration occurs mostly in the 21st century 642 is concentrated in a few hotspotactive regions with 70 percent of the total sink occurring in less than 40 percent of 643 644 the global ocean. We analyze the results from the CMIP6 multi-model mean for the current state of the ocean (1995-2015), and the middle (2040-2060) and late (2080-2100) 21st century relative to the current state for three 645 scenarios. We show that future changes in the sink are projected to mostly take place within the same historical 646 hotspothighly active regions. This result implies that known regions of high historical uptake, including the North 647 648 Atlantic and Southern Ocean, are the same regions to prioritize for observing the future evolution of the sink. Our results extend the argument of Wang et al. (2016) that the historical state is a good predictor of the future state to 649 spatial patterns of change. 650

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652 We show that the CMIP6 multi-model mean provides a consistent estimate of the spatial patterns of the sink, and the trend in the sink (globally), compared to the observation-based data product dataset of Landschützer et al. 653 654 (2016). These results suggest the CMIP6 models are valid tools for understanding the past and future evolution of the ocean carbon sink, particularly at broad spatial scales. A notable area of disagreement is that the Landschützer 655 et al. (2016) data shows larger decadal variability at the global scale than seen in any CMIP6 model. We argue and 656 the overestimation range of internal variability by this dataset is a plausible explanation, since at the regional scale, 657 there is no such disagreement. This is in agreement with from CanESM5 large ensemble. Gloege et al. (2021) who 658 showedshows that the SOM-FFN method overestimates the magnitude of decadal variability by 21% on the global 659 scale due to the amount of gap filling. 660

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We have shown that the magnitude of uncertainty and its partitioning among different sources differs with scale and location. On the global scale, scenario uncertainty is the largest source of uncertainty followed by model

uncertainty and internal variability. However, as for CMIP6 models. These results are in agreement with previous 664 studies form CMIP5 models (Lovenduski et al., 2016; Schlunegger et al., 2020). As the scales of integration 665 (averaging) get finer, model and internal variability become the dominant sources, respectively. Testing the results 666 on two ocean basins regions of about the same size, one in the NE Pacific and one in the NW Atlantic shows that -667 while consistent with the results of the scale dependence analysis - the relative importance of the sources of 668 uncertainty also differs with location. Notably, in hotspotOur test here extends the analysis Schlunegger et al. 669 (2020) with a focus on the association of the location dependence with whether the regions have highly active 670 carbon sinks. Notably, in highly active regions, such as the NW Atlantic, scenario uncertainty is large, whereas in 671 more quiescent regions, such as the NE Pacific, internal variability is more significant. The dependence of internal 672 variability on the scenario with time is another interesting finding that could be the subject of future studies for a 673 better understanding of the driving mechanism and the degree of dependence on the future emissions and/or 674 675 concentrations.

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The patterns of high future CO_2 uptake uncertainty are highly correlated with the patterns of historical uptake. The correlation coefficients are highest for scenario uncertainty, indicating that the hotspothighly active regions have the potential for the sink to evolve according to the atmospheric CO_2 concentration, while the rest of the ocean basins do not respond strongly to changes in atmospheric CO_2 represented by the different scenarios. This finding has implications for assessment of the mitigations and effects of socioeconomic decisions. Our results here are significant in that they show that regions of future uncertainty are largely associated with known regions of significant historical uptake.

684

Patterns seen in the time-of-emergence have implications for planning observational campaigns for detection of a 685 signal- (Schlunegger et al. 2019 & 2020). Furthermore, there is reverse association between how sensitive a region 686 is to scenario differences (apparent in the scenario uncertainty patterns) and how sensitive the TOE is to scenarios. 687 Our results show that there caution should be caution taken in interpreting the observed changes in regions such as 688 689 NE Pacific (where active sampling is being done) associated with the late with late time of emergence of the signal from the decadal (internal) variations. On the other hand, regions such as the Equatorial Pacific, the Gulf Stream 690 and Kuroshio and their extensions, and the Southern Ocean, should be the focus of consistent and expanded 691 692 sampling for detection of the forced signal. Additionally, the patterns in sources of uncertainty show that model uncertainty is largest in the Southern Ocean, consistent with previous studies. Frölicher et al., 2015. The sink in the 693 694 Southern Ocean is driven by complex mechanisms involving coupled ocean-atmosphere-ice interactions that require better representation in ocean biogeochemical models. If we wish to constrain and reduce futureSignificant progress in reducing uncertainties in the ocean carbon sink, ourcan be expected from new methods of bringing together models and observations (Frolicher et al. 2016). Our results provide a motivation to focus modelling as well as observational efforts on the known hotspothighly active regions of historical uptake.

Finally, we have shown that internal variability shows clear changes in time and depends on the scenario. The 700 emergence of Large Ensembles (LEs) allows for quantification of these variations if enough ensemble members 701 are available to fully capture internal variability using realizations that start from different initial conditions. Our 702 use of the CanESM5 LE allows for us to account for the nonstationary of internal variability in time, like in 703 Schlunegger et al. (2020) but with the advantage of also accounting for scenario dependence. Model 704 intercomparison indicates that ESMs show differences in natural variability (Schlunegger et al. 2020). Nonetheless, 705 our analysis of the global scale, of scale dependence, and of the patterns seen in Time of Emergence are consistent 706 with previous studies, despite the potential sensitivity to the use of CanESM5 LE. Our methodology to correct for 707 internal variability from model spread, without filtering or having a large ensemble for each ESM (which would 708 limit the number of ESMs that can be included and, consequently, underestimate model uncertainty) lays the 709 710 foundation for future studies when LEs are available from more ESMs and advocates for more modelling groups to provide such LEs in order to achieve an even more robust estimate of internal variability as the mean across 711 712 different ESMs.

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714 Data Availability

The data used in this study is part of the World Climate Research Programme's (WCRP) 6th Coupled Model
Intercomparison Project (CMIP6) open access data. For details on accessibility see section S1 in the Supplements.
The SOM-FFN data (Landschützer et al., 2017) from Landschützer (2016) can be accessed through the <u>National</u>
<u>Oceanographic Data Center</u> (NODC, https://www.nodc.noaa.gov/archive/arc0105/0160558/3.3/data/0-data/)
operated by the National Oceanic and Atmospheric Administration (NOAA) of the U.S. Department of Commerce.

720 Author Contribution

- 721 Parsa Gooya conducted the formal analysis, visualization, and original draft preparation. Conceptualization, and
- methodology development and validation were a collaboration of the three authors, mainly developed by Parsa
- 723 Gooya with contributions from Neil Swart in development, validation, and revision and Roberta Hamme in
- validation and revision. Neil Swart and Roberta Hamme provided supervision and reviewing and editing of the
- 725 manuscript and methodology. Funding acquisition was carried out by Roberta Hamme.

726 Competing of interest

727 The authors declare that they have no conflict of interest.

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