



*Supplement of*

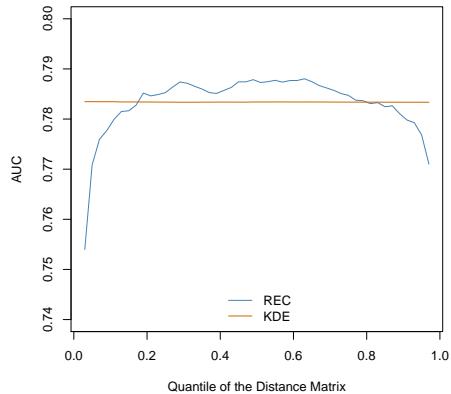
## **Multivariate anomaly detection for Earth observations: a comparison of algorithms and feature extraction techniques**

**Milan Flach et al.**

*Correspondence to:* Milan Flach (milan.flach@bgs-jena.mpg.de)

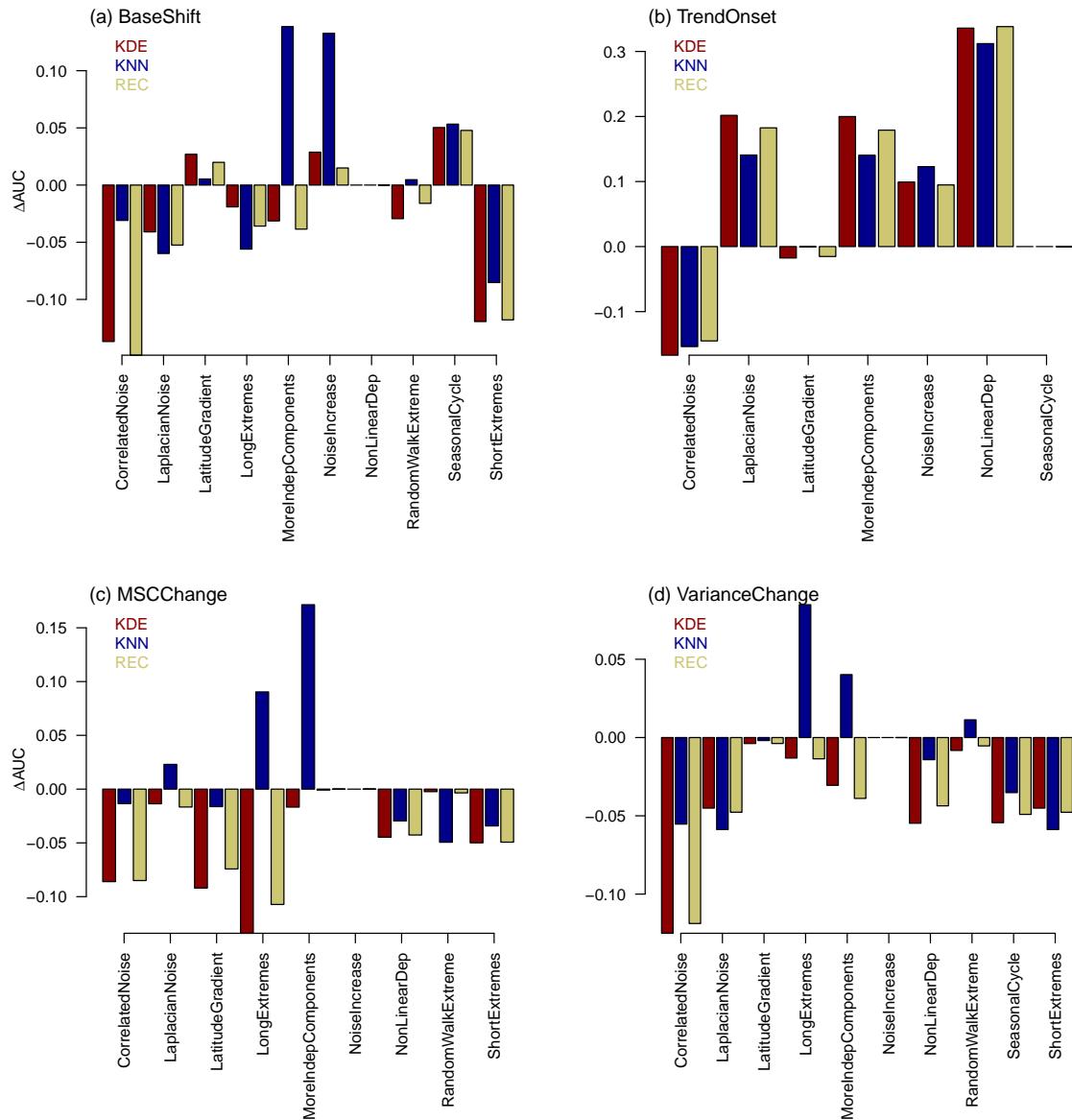
The copyright of individual parts of the supplement might differ from the CC BY 3.0 License.

## Supplementary Material 1 Parameterization of Recurrences and Kernel Density Estimation



**Figure S1.** We test different choices of  $\sigma$  (Recurrences (*REC*)) or  $\varepsilon$  (for Kernel Density Estimation (*KDE*)) in a small simulation (500 repetitions) trying to detect a BaseShift.  $\sigma$  (or  $\varepsilon$ , respectively) is varied between the 0.05 and 0.95 quantile of the distribution of values of the distance matrix. The Area Under the receiver operator characteristics Curve (*AUC*) is computed for each parameterization. Results exhibit constant *AUC* values for *KDE* within the testing range of  $\sigma$ . In contrast *REC* is more sensitive to the choice of  $\varepsilon$ , although it might yield slightly higher *AUC* values in case of optimal chosen  $\varepsilon$ .

## Supplementary Material 2 Effect of different data properties on the algorithms



**Figure S2.** Effect of different data properties on the 3 best detection algorithms (KDE, REC, KNN-Gamma) presented as AUC difference to the UNIV control for the event types (a-d). Details for each algorithm reveal that KNN-Gamma is often less affected by 'difficult' data properties like CorrelatedNoise or MoreIndepComponents, i.e. KNN-Gamma is more adaptive than the other two algorithms.