



Supplement of

Emulating Earth system model temperatures with MESMER: from global mean temperature trajectories to grid-point-level realizations on land

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Shapiro-Wilk test for normality with controlling the false discovery rate at $\alpha_{FDR} = 0.1$

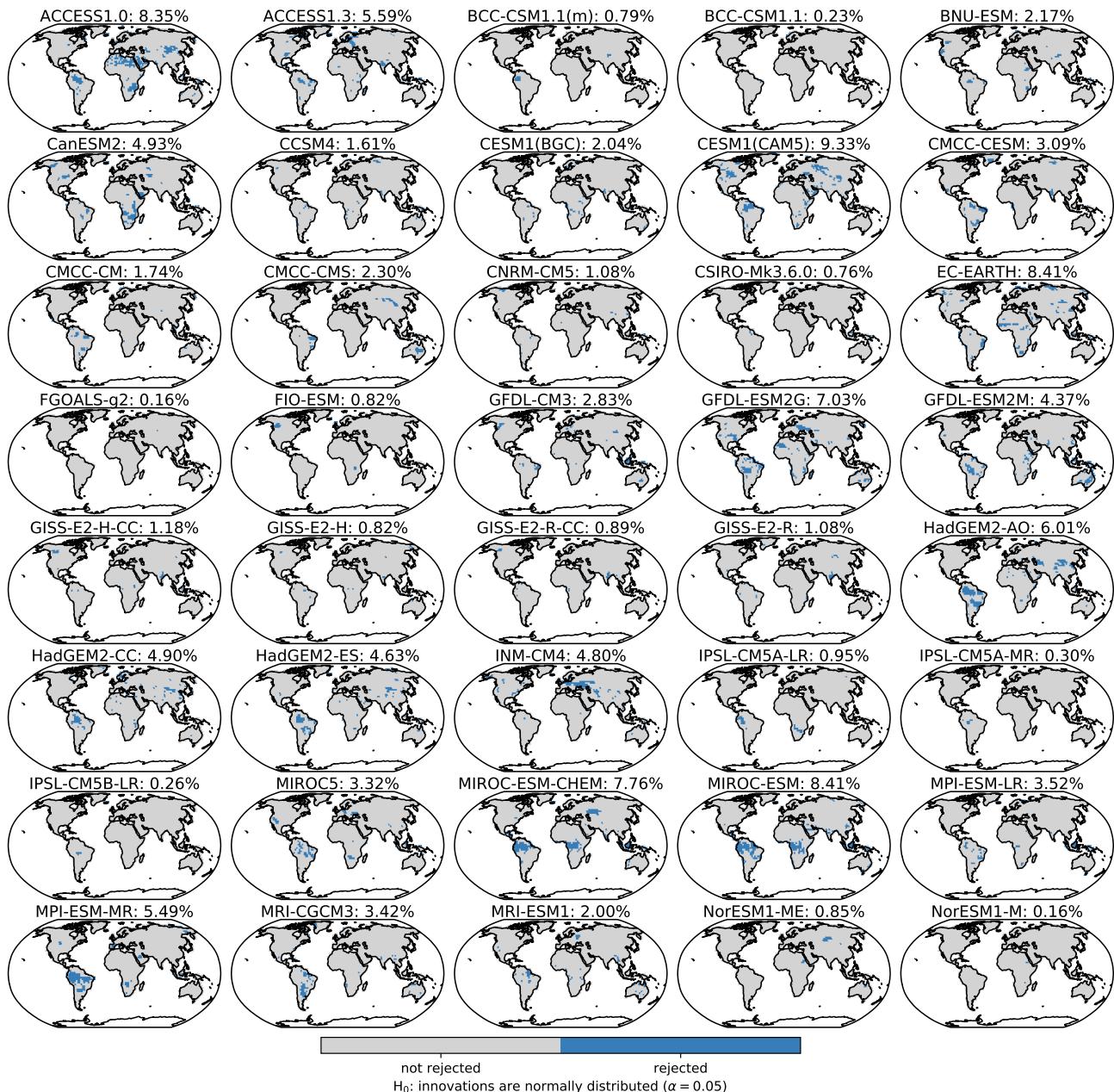


Figure S1. Shapiro-Wilk test for normality with H_0 : the data are normally distributed (Steinskog et al., 2007) and controlling the False Discovery Rate (FDR, Wilks, 2016) at 10 % for the local residual variability innovations $\nu_{s,t}$ of the training runs.

Emulator calibration parameters

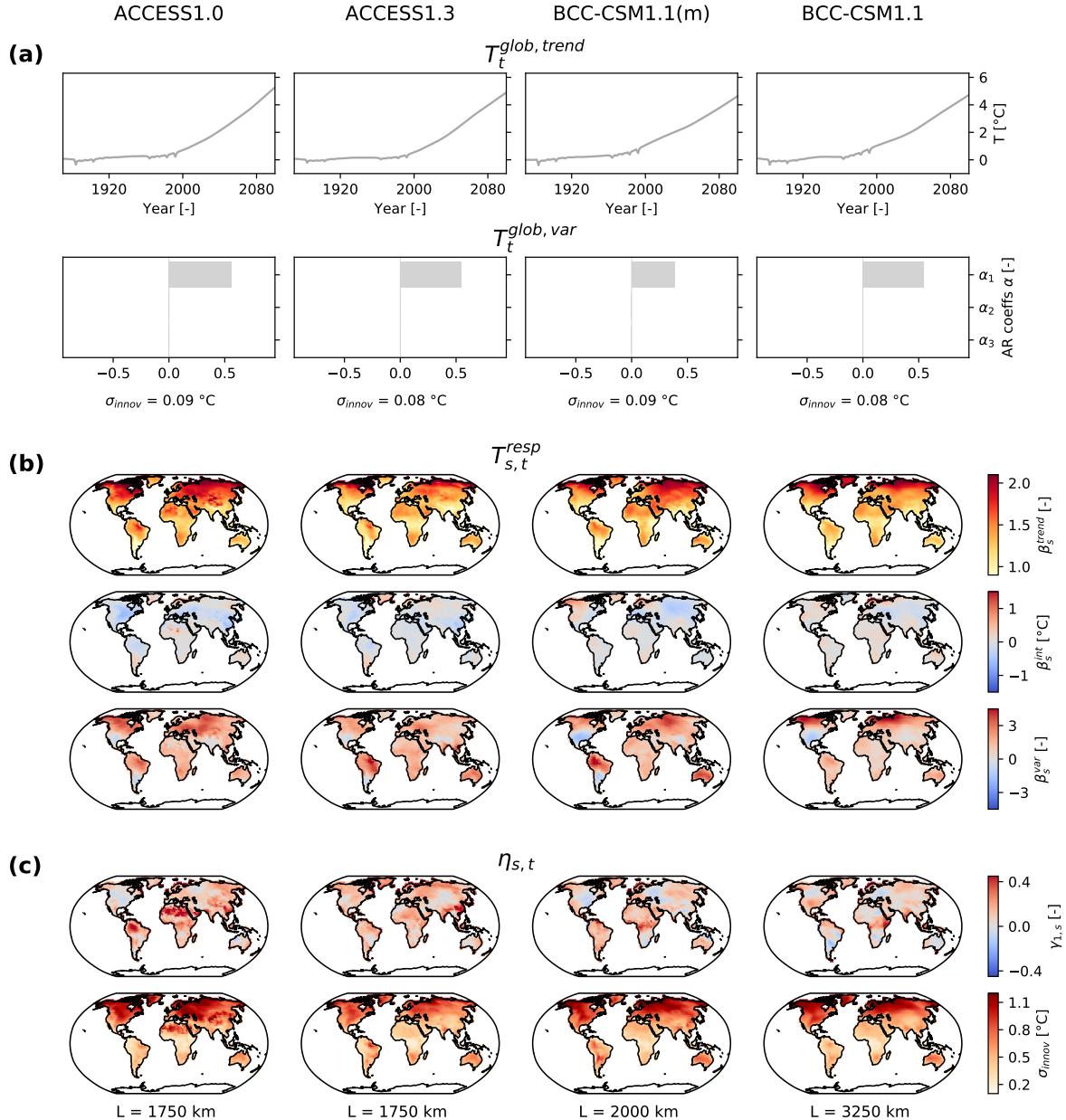


Figure S2. Emulator calibration parameters (rows) for four climate models (columns). Analogous to Fig. 3 for ACCESS1.0, ACCESS1.3, BCC-CSM1.1(m), and BCC-CSM1.1.

Emulator calibration parameters

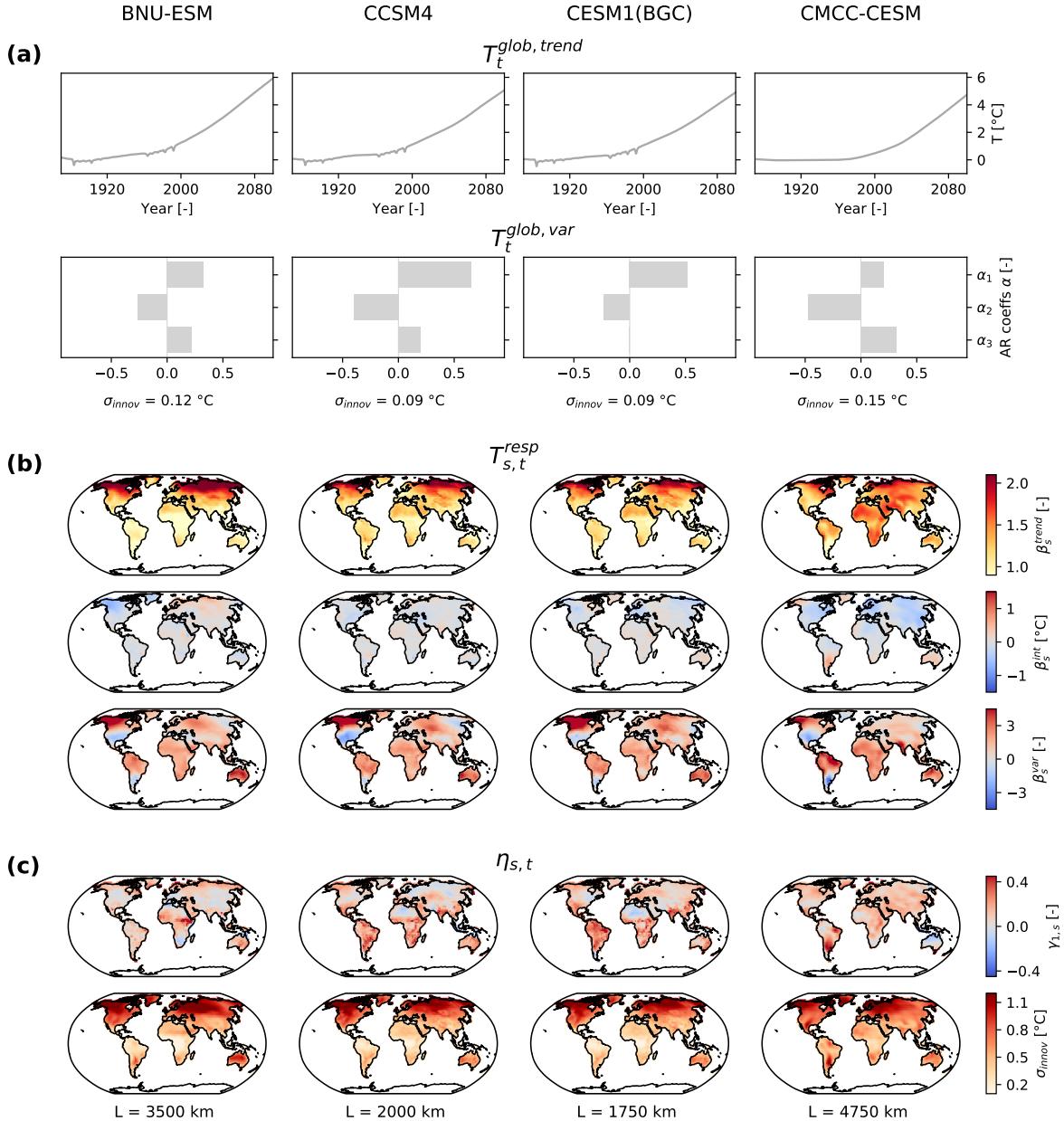


Figure S3. Emulator calibration parameters (rows) for four climate models (columns). Analogous to Fig. 3 for BNU-ESM, CCSM4, CESM1(BGC), and CMCC-CESM.

Emulator calibration parameters

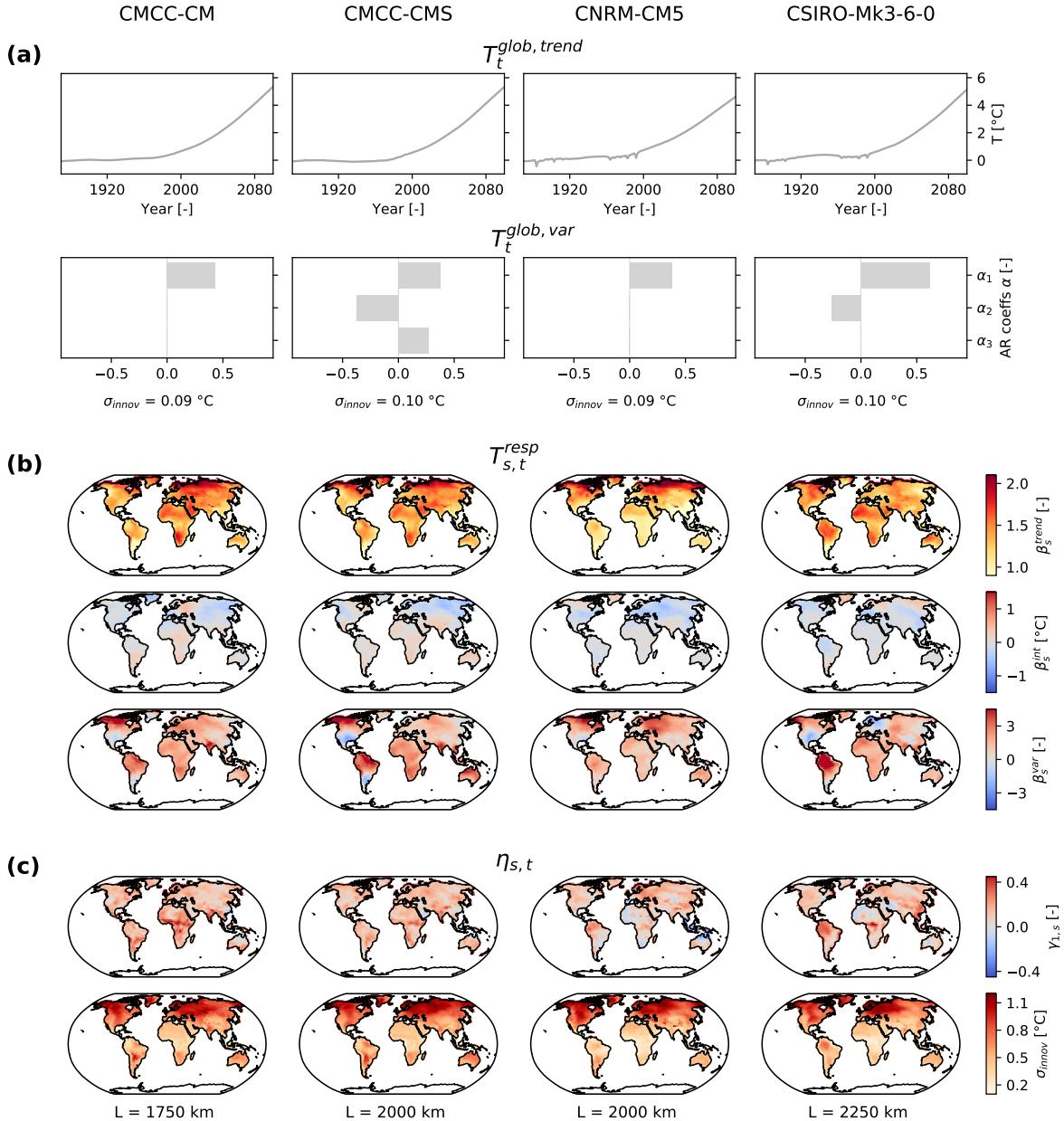


Figure S4. Emulator calibration parameters (rows) for four climate models (columns). Analogous to Fig. 3 for CMCC-CM, CMCC-CMS, CNRM-CM5, and CSIRO-Mk3.6.0.

Emulator calibration parameters

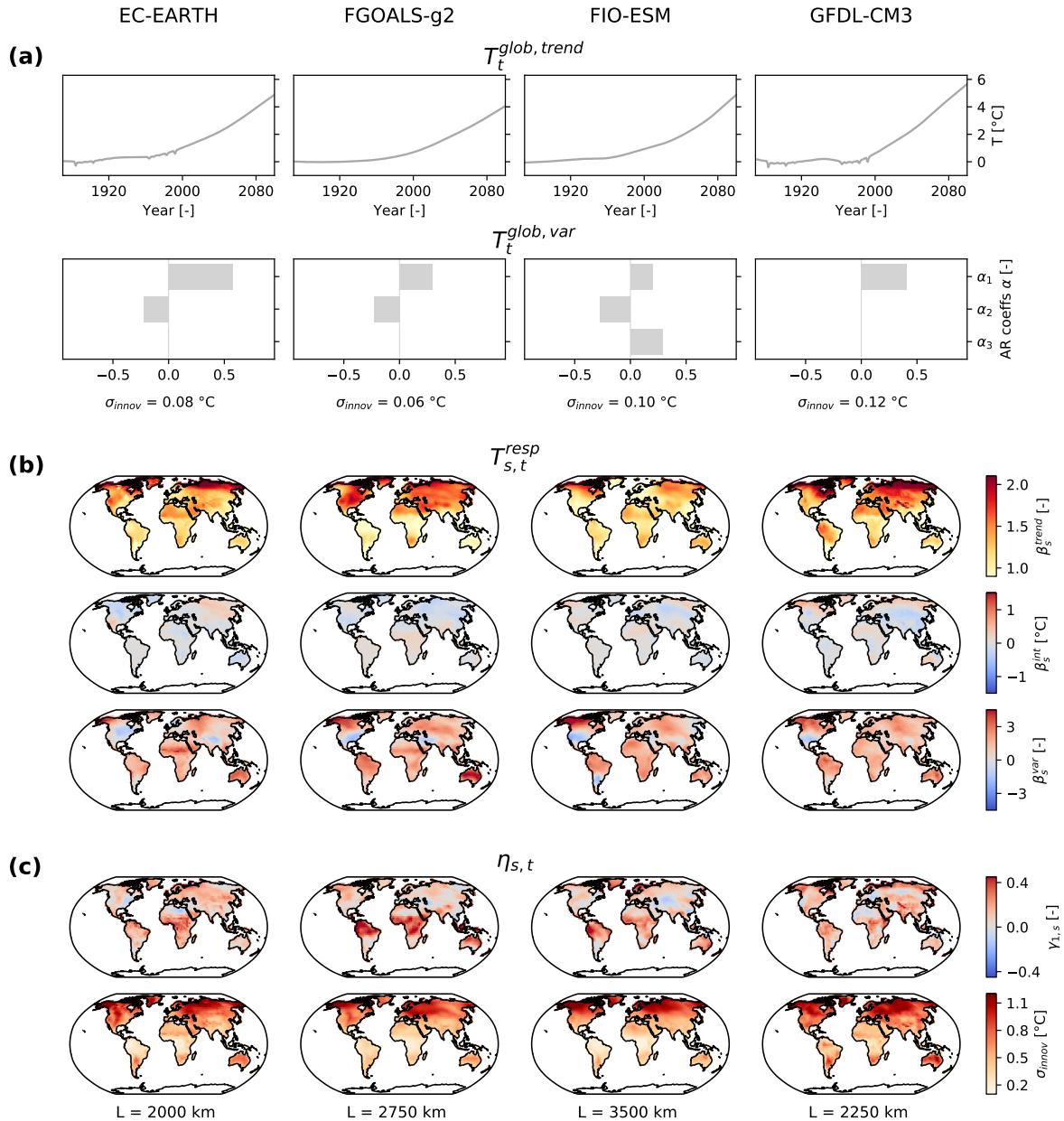


Figure S5. Emulator calibration parameters (rows) for four climate models (columns). Analogous to Fig. 3 for EC-EARTH, FGOALS-g2, FIO-ESM, and GFDL-CM3.

Emulator calibration parameters

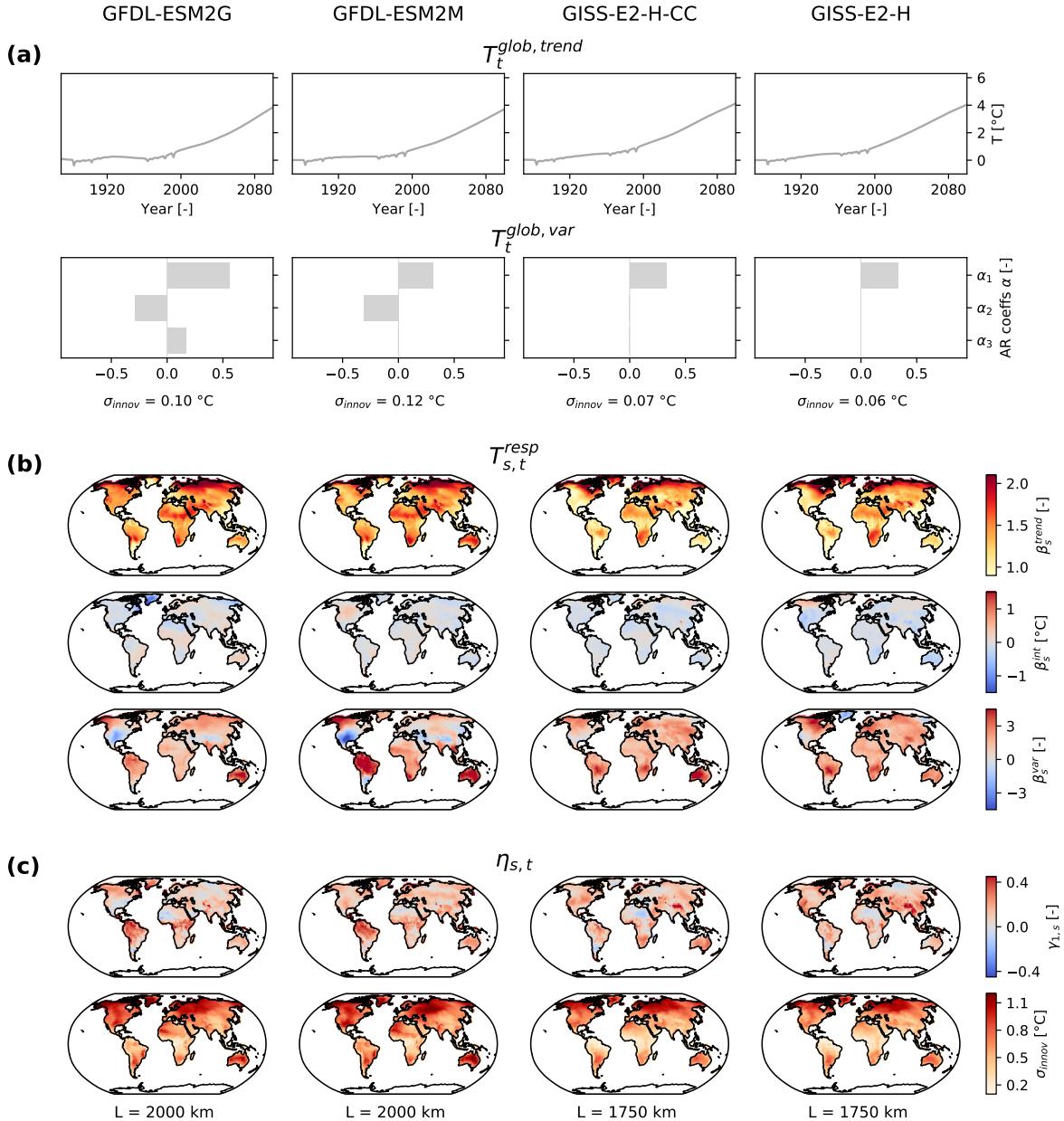


Figure S6. Emulator calibration parameters (rows) for four climate models (columns). Analogous to Fig. 3 for GFDL-ESM2G, GFDL-ESM2M, GISS-E2-H-CC, and GISS-E2-H.

Emulator calibration parameters

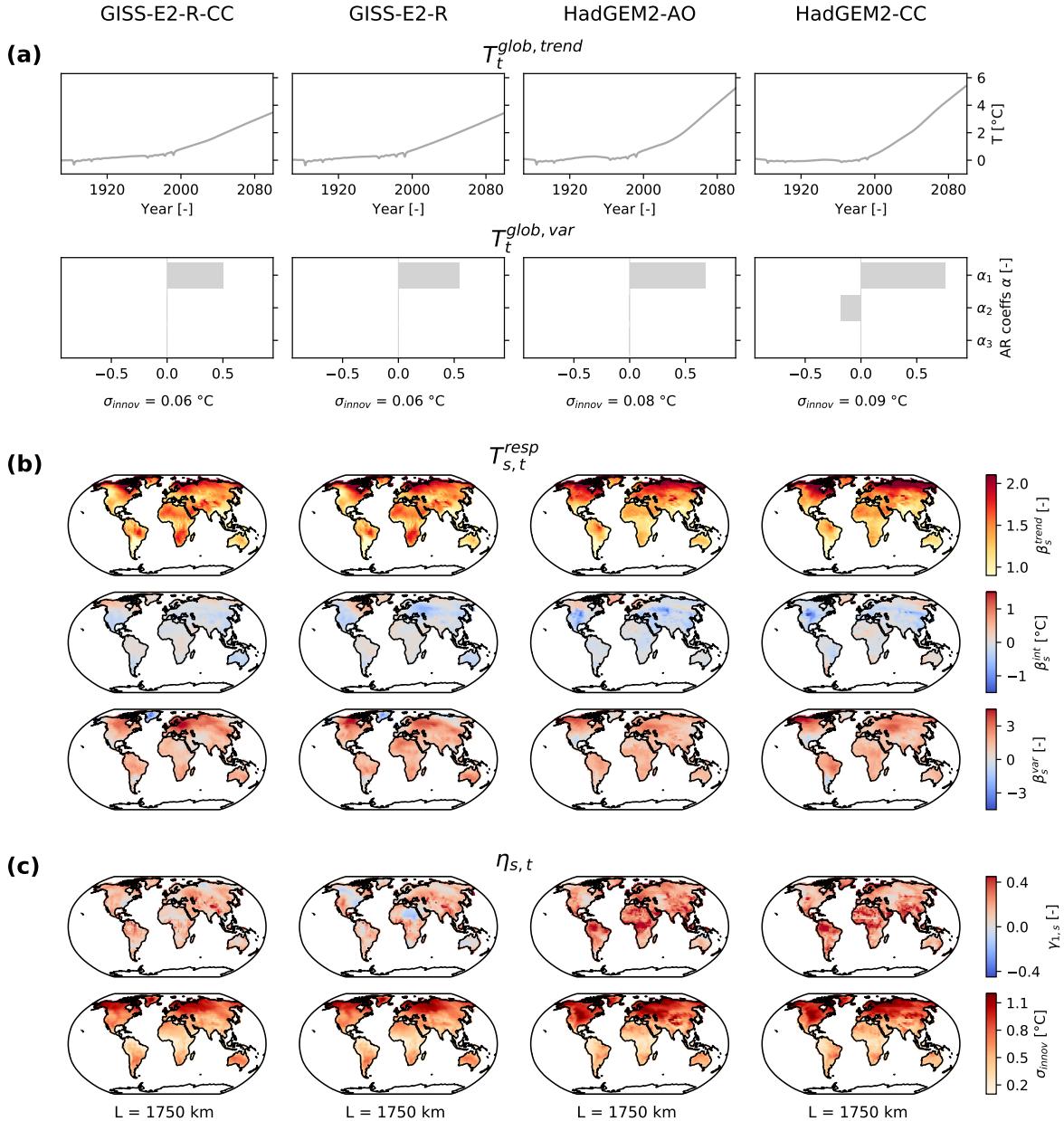


Figure S7. Emulator calibration parameters (rows) for four climate models (columns). Analogous to Fig. 3 for GISS-E2-R-CC, GISS-E2-R, HadGEM2-AO, HadGEM2-CC.

Emulator calibration parameters

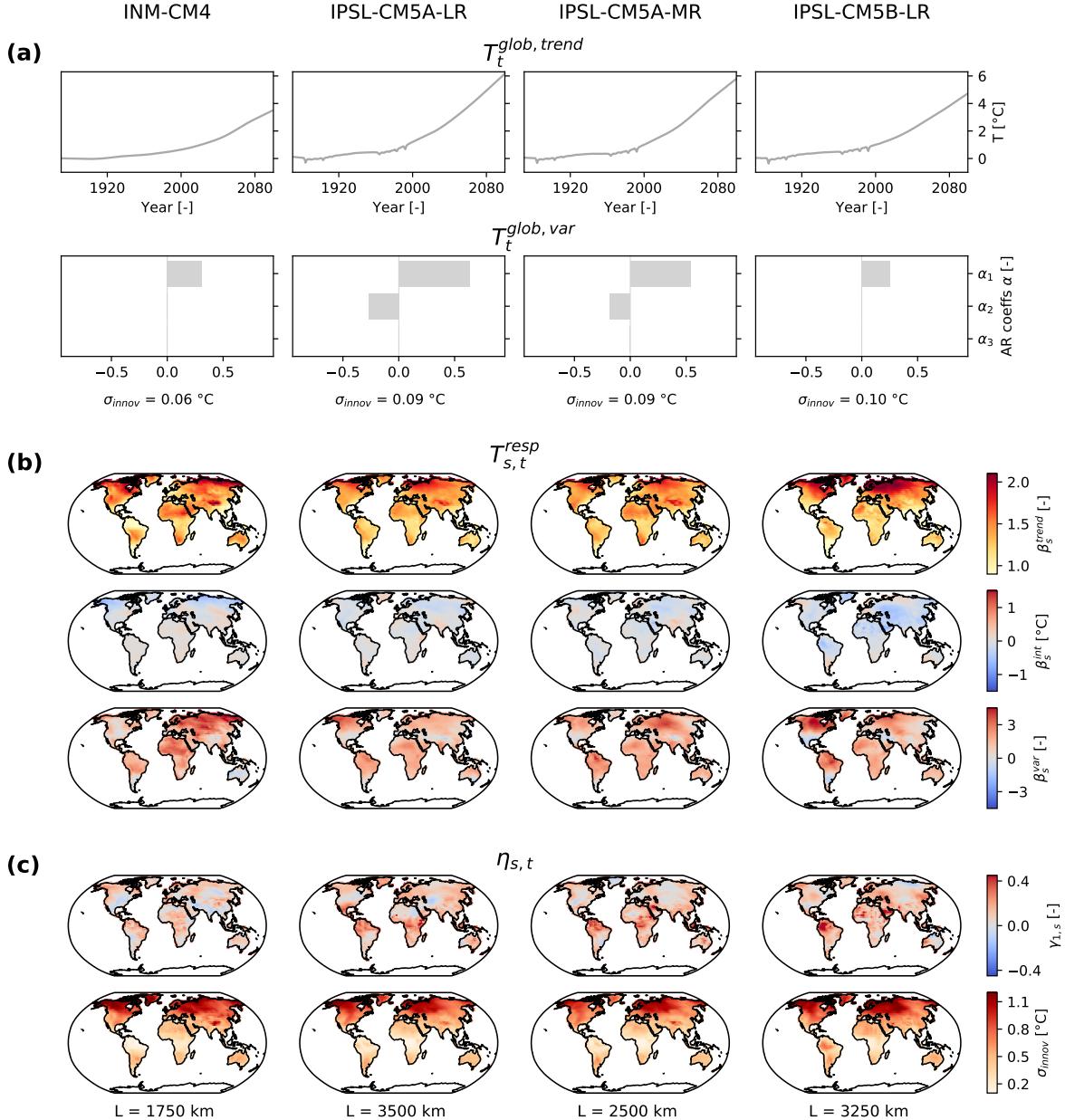


Figure S8. Emulator calibration parameters (rows) for four climate models (columns). Analogous to Fig. 3 for INM-CM4, IPSL-CM5A-LR, IPSL-CM5A-MR, and IPSL-CM5B-LR.

Emulator calibration parameters

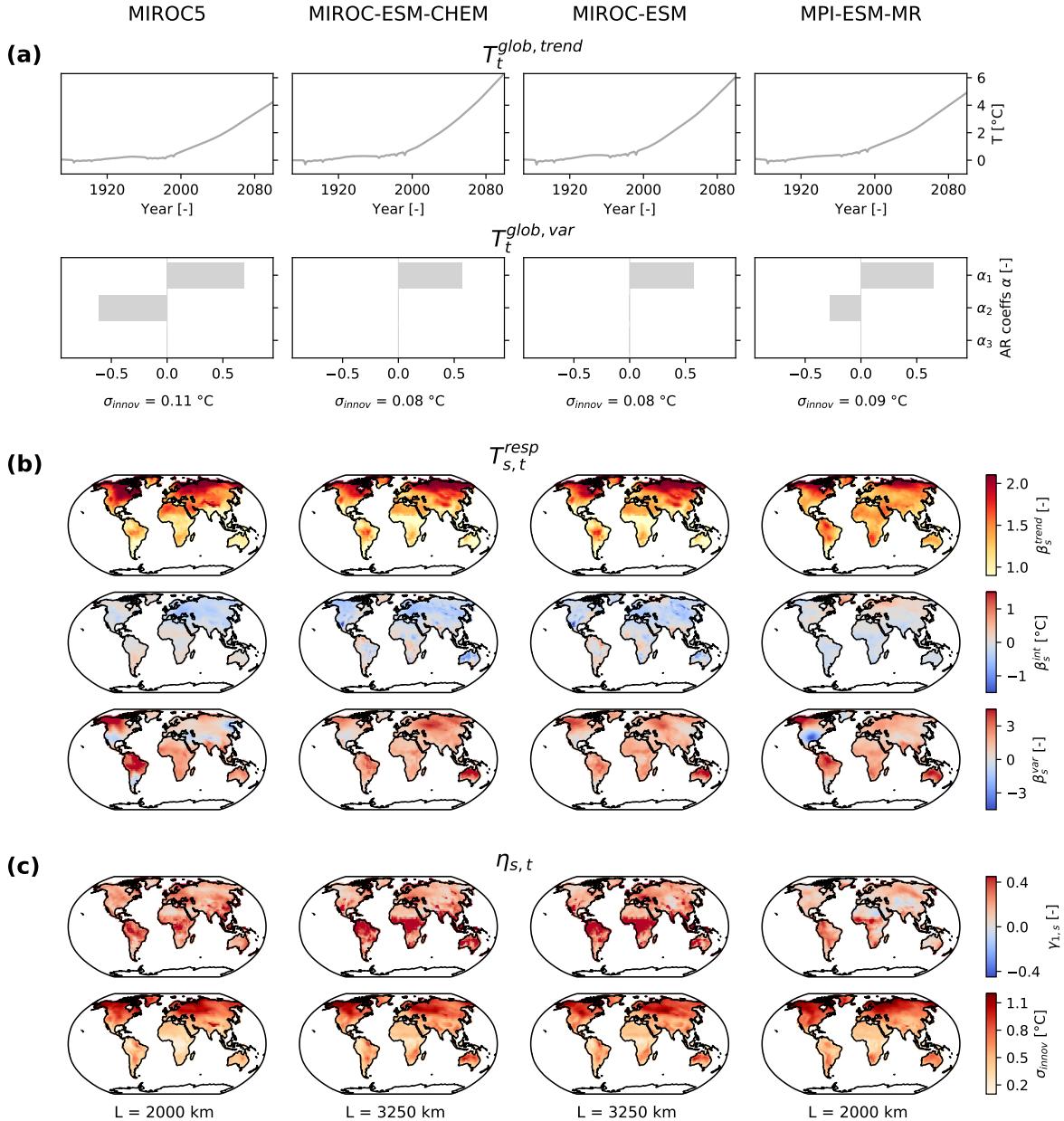


Figure S9. Emulator calibration parameters (rows) for four climate models (columns). Analogous to Fig. 3 for MIROC5, MIROC-ESM-CHEM, MIROC-ESM, and MPI-ESM-MR.

Emulator calibration parameters

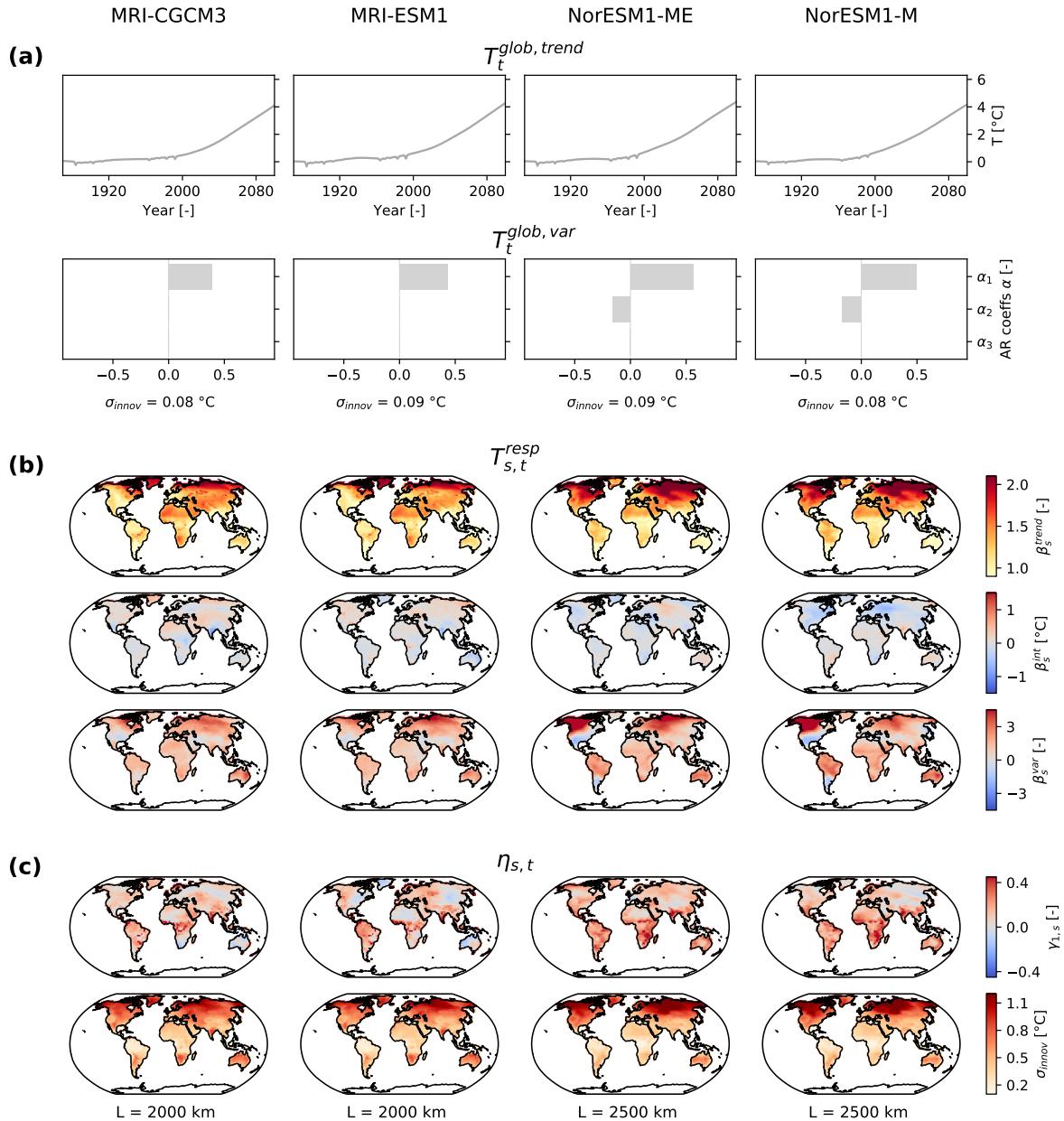


Figure S10. Emulator calibration parameters (rows) for four climate models (columns). Analogous to Fig. 3 for MRI-CGCM3, MRI-ESM1, NorESM1-ME, and NorESM1-M.

Comparing ESM runs, full emulations, and simple pattern scaling results
for CESM1(CAM5) in different regions

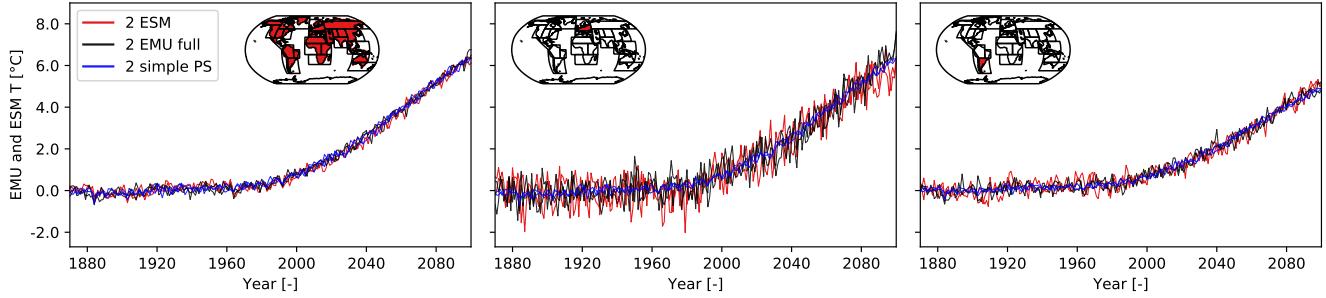


Figure S11. Comparison of regionally averaged temperature time series for CESM1(CAM5) test runs (red), full emulations (black), and simple pattern scaling results (blue) in three regions. The regions are (from left to right): global land, Central Europe (CEU), and Southeastern South America (SSA). The pattern scaling results at each grid point and time step are obtained by $T_{s,t}^{ps} = \beta_{1,s}^{ps} \cdot T_t^{glob} + \beta_{0,s}^{ps}$ with the coefficients $\beta_{1,s}^{ps}$ and $\beta_{0,s}^{ps}$ fit with the Ordinary Least Squares (OLS) algorithm on the training run.

References

- Steinskog, D. J., Tjøstheim, D. B., and Kvamstø, N. G.: A Cautionary Note on the Use of the Kolmogorov–Smirnov Test for Normality, Monthly Weather Review, 135, 1151–1157, <https://doi.org/10.1175/mwr3326.1>, 2007.
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